Aequationes Mathematicae



On Wendel's equality for intersections of balls

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Abstract. We study the analogue of Wendel's equality in random polytope models in which the hull of the random points is formed by intersections of congruent balls, called the spindle (or hyper-) convex hull. According to the classical identity of Wendel the probability that the origin is contained in the (linear) convex hull of n i.i.d. random points distributed according to an origin symmetric probability distribution in the d-dimensional Euclidean space \mathbb{R}^d that assigns measure zero to hyperplanes is a constant depending only on n and d. While in the classical convex case one gets nonzero probabilities only for $n \ge d+1$ points in \mathbb{R}^d , for the spindle convex hull this happens for all $n \ge 2$. We study this question for the uniform and normally distributed random models.

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1. Introduction and results

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Wendel's equality [10] is one of the classical results in geometric probability: it states that if x_1, \ldots, x_n are i.i.d. random points in \mathbb{R}^d whose distribution is (centrally) symmetric with respect to the origin o, and the probability measures of hyperplanes are 0, then the probability that o is not contained in the convex hull $[x_1, \ldots, x_n]$ is

$$\mathbb{P}(o \notin [x_1, \dots, x_n]) = \frac{1}{2^{n-1}} \sum_{i=0}^{d-1} \binom{n-1}{i}.$$
(1.1)

One can find a simple proof of (1.1) in Bárány [1, pp. 94-95], which is independent of the distribution (under the above conditions).

It was proved by Wagner and Welzl [9], that *o*-symmetric distributions are extremal in this sense. For more information, see also [8, Section 8.1.2].

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Recently, Kabluchko and Zaporozhets [3] investigated the related problem of finding the probability that the convex hull of n i.i.d. normally distributed random points in \mathbb{R}^d contains a fixed points of space; they called these *absorption probabilities*. For a general introduction to random polytopes we refer to the recent survey paper by Schneider [7] and the book by Schneider and Weil [8].

We denote the *d*-dimensional origin centered unit radius closed ball by B^d and its boundary by S^{d-1} . The symbol κ_d denotes the volume (Lebesgue measure) of B^d , and ω_d is the surface volume of B^d . For general information on convex sets, see the monograph [6] by Schneider.

In this paper we study the following spindle convex variant of the above problems. Let $x, y \in \mathbb{R}^d$ be two points and $\rho > 0$. If $|x - y| \leq 2\rho$, then let the spindle $[x, y]_{\rho}$ determined by x and y be the intersection of all radius ρ closed balls that contain both x and y. If $|x - y| > 2\rho$, then let $[x, y]_{\rho} = \mathbb{R}^d$. We say that a convex body $K \subset \mathbb{R}^d$ (compact convex set with non-empty interior) is spindle convex with radius ρ , or ρ -spindle convex if together with any two points $x, y \in K$, it contains the spindle $[x, y]_{\rho}$. It is known ([2]) that if a convex body $K \subset \mathbb{R}^d$ is spindle convex with radius ρ , then K is the intersection of all radius ρ closed balls that contain K. This latter property is called radius ρ ball-convexity.

Let $X \subset \mathbb{R}^d$. If $X \subset \rho B^d + v$ for some $v \in \mathbb{R}^d$, then the radius ρ spindle convex hull $[X]_{\rho}$ of K is defined as the intersection of all radius ρ closed balls containing X. If $X \not\subset \rho B^d + v$ for any $v \in \mathbb{R}^d$, then let $[X]_{\rho} = \mathbb{R}^d$. If $K \subset \mathbb{R}^d$ is spindle convex with radius ρ , and $X \subset K$, then $[X]_{\rho} \subset K$. For more information on spindle convexity, see, for example, the paper [2] by Bezdek et al. and the book [4] by Martini, Montejano and Oliveros and the references therein.

First, we describe the ρ -spindle convex uniform model. Let $\rho > 0$, and let $K \subset \mathbb{R}^d$ be an ρ -symmetric convex body that is ρ -spindle convex. Let x_1, \ldots, x_n be i.i.d. uniform random points from K. We denote the radius ρ spindle convex hull of x_1, \ldots, x_n by $K^{\rho}_{(n)} = [x_1, \ldots, x_n]_{\rho}$. By the ρ -spindle convexity of K, the random ball-polytope $K^{\rho}_{(n)}$ is contained in K. We ask the same question as in the classical convex case: what is the probability that $o \in K^{\rho}_{(n)}$? We note that in this model we may always achieve by scaling (simultaneously K and radius ρ circles) that $\rho = 1$. Henceforth, in the following two theorems we assume that $\rho = 1$.

We study the special case when $K = rB^d$ with $0 < r \le 1$. Then K is clearly spindle convex with radius $\rho = 1$. We wish to determine the probability

$$P(d, r, n) := \mathbb{P}(o \in [x_1, \dots, x_n]_1).$$

In Sect. 2 we prove the following theorem:

Theorem 1.1. Let $K = rB^d$. Then

$$P(d,r,2) = \frac{\omega_{d-1}\omega_d}{(r^d\kappa_d)^2} \int_0^r \int_0^r \int_0^{\varphi(r_1,r_2)} r_1^{d-1} r_2^{d-1} \sin^{d-2}\varphi \, d\varphi dr_2 dr_1,$$

where $\varphi(r_1, r_2) = \arcsin(r_1/2) + \arcsin(r_2/2)$. In particular,

$$P(2,1,2) = \frac{\sqrt{3}}{\pi} - \frac{1}{3} = 0.2179...,$$

$$P(3,1,2) = \frac{1}{64}(23 + 12\sqrt{3}\pi - 8\pi^2) = 0.1459....$$

Furthermore, for the case of three points, we prove the following statement in Sect. 3.

Theorem 1.2. Let $K = B^2$. Then

$$P(2,1,3) = \frac{-84\pi^2 - 477 + 360\sqrt{3}\pi}{144\pi^2} = 0.4594\dots$$

Finally, in Sect. 4, we study the Gaussian ρ -spindle convex model. Let x_1, \ldots, x_n be i.i.d. random points from \mathbb{R}^d distributed according to the standard normal distribution. The question is the same, what is the probability that $o \in K_{(n)}^{\varrho}$? We note that in this second case, it may, and does, happen that $K_{(n)}^{\varrho} = \mathbb{R}^d$. We give an integral formula for the probability that a Gaussian unit radius spindle contains the origin and evaluate it numerically in the plane.

2. Proof of Theorem 1.1

Note that it is the simplest case of the model when n = 2, and $K = rB^d$, where $0 < r \leq 1$ is a fixed number. This, of course, is of no interest in the classical version of Wendel's problem as $\mathbb{P}(o \in [x_1, x_2]) = 0$ since $[x_1, x_2]$ is a segment.

Let us examine what it means geometrically that $o \in [x_1, x_2]_1$. Let $M(x_1)$ denote the union of all open unit balls that contain o and x_1 on their boundary. Let $K(d, r, x_1)$ be the part of $rB^d \setminus M(x_1)$ that is in the closed half-space bounded by the hyperplane through o and orthogonal to x_1 which does not contain x_1 . We depicted this region in Fig. 1 when d = 2. We will only use $K(2, r, x_1)$ in our calculations, so, in order to simplify notation, we will denote it by $K(r, x_1) = K(2, r, x_1)$.

In order to evaluate P(d, r, 2), we use the linear Blaschke-Petkantschin formula. Let G(d, 2) denote the Grassmannian manifold of 2-dimensional linear subspaces of \mathbb{R}^d , and ν_2 be the unique rotation invariant Haar probability measure on G(d, 2). The 2-dimensional special case of the linear Blaschke-Petkantschin formula (see, for example, [8, Theorem 7.2.1 on p. 271]) says the following: If $f : (\mathbb{R}^d)^2 \to \mathbb{R}$ is a non-negative measurable function, then



FIGURE 1. The region $K(r, x_1)$

$$\int_{(\mathbb{R}^d)^2} f \, d\lambda^2 = \frac{\omega_{d-1}\omega_d}{\omega_1\omega_2} \int_{G(d,2)} \int_{L^2} f(x_1, x_2) \nabla_2^{d-2}(x_1, x_2) \, d\lambda_L^2 \, \nu_2(dL),$$
(2.1)

where ∇_2 denotes the area of the parallelogram spanned by the vectors x_1, x_2 in *L*. The symbol λ denotes the Lebesgue measure in \mathbb{R}^d , and λ_L the (2dimensional) Lebesgue measure in *L*.

Next, using polar coordinates for $x_1, x_2 \in L$, that is, $x_1 = r_1 u_1, x_2 = r_2 u_2$, where $u_1, u_2 \in S^1$, $r_1, r_2 \in \mathbb{R}_+$, we may write the right-hand-side of (2.1) as follows.

$$\frac{\omega_{d-1}\omega_d}{\omega_1\omega_2} \int_{G(d,2)} \int_{L^2} f(x_1, x_2) \nabla_2^{d-2}(x_1, x_2) \, d\lambda_L^2 \, \nu_2(dL) \\
= \frac{\omega_{d-1}\omega_d}{\omega_1\omega_2} \int_{G(d,2)} \int_{(S^1 \times \mathbb{R})^2} f(r_1u_1, r_2u_2) \\
\times \nabla_2^{d-2}(r_1u_1, r_2u_2) \, r_1r_2 dr_1 du_1 dr_2 du_2 \, \nu_2(dL) \\
= \frac{\omega_{d-1}\omega_d}{\omega_1\omega_2} \int_{G(d,2)} \int_{(S^1 \times \mathbb{R})^2} f(r_1u_1, r_2u_2) r_1^{d-1} r_2^{d-1} \times \\
\times |u_1 \times u_2|^{d-2} dr_1 du_1 dr_2 du_2 \, \nu_2(dL). \tag{2.2}$$

Now, from (2.2) we obtain that

$$P(d,r,2) = \frac{1}{(r^{d}\kappa_{d})^{2}} \int_{rB^{d}} \int_{rB^{d}} \mathbf{1}(o \in [x_{1}, x_{2}]_{1}) dx_{1} dx_{2}$$
$$= \frac{1}{(r^{d}\kappa_{d})^{2}} \frac{\omega_{d-1}\omega_{d}}{\omega_{1}\omega_{2}} \int_{G(d,2)} \int_{S^{1}} \int_{0}^{r} \int_{S^{1}} \int_{0}^{r} \mathbf{1}(o \in [r_{1}u_{1}, r_{2}u_{2}]_{1}) r_{1}^{d-1} r_{2}^{d-1}$$

$$\begin{aligned} & \times |u_1 \times u_2|^{d-2} dr_1 du_1 dr_2 du_2 \,\nu_2(dL) \\ &= \frac{1}{(r^d \kappa_d)^2} \frac{\omega_{d-1} \omega_d}{\omega_1 \omega_2} \int_{S^1} \int_0^r \int_{S^1} \int_0^r \mathbf{1}(o \in [r_1 u_1, r_2 u_2]_1) r_1^{d-1} r_2^{d-1} \\ & \times |u_1 \times u_2|^{d-2} dr_1 du_1 dr_2 du_2 \\ &= \frac{1}{(r^d \kappa_d)^2} \frac{\omega_{d-1} \omega_d}{\omega_1 \omega_2} \int_{S^1} \int_0^r \int_{S^1} \int_0^r \mathbf{1}(x_2 \in K(r, x_1)) r_1^{d-1} r_2^{d-1} \\ & \times |u_1 \times u_2|^{d-2} dr_2 du_2 dr_1 du_1. \end{aligned}$$

By the rotational symmetry of rB^d , integration with respect to u_1 is a multiplication by 2π . Hence, from now on, we fix $u_1 = (0, 1)$. Let φ be the angle of u_2 and $-u_1$, as shown on Fig. 1, and let

$$\varphi(r_1, r_2) = \arcsin(r_1/2) + \arcsin(r_2/2).$$

Then

$$P(d,r,2) = \frac{2\pi}{(r^{d}\kappa_{d})^{2}} \frac{\omega_{d-1}\omega_{d}}{\omega_{1}\omega_{2}} \int_{0}^{r} \int_{0}^{r} \int_{-\varphi(r_{1},r_{2})}^{\varphi(r_{1},r_{2})} r_{1}^{d-1} r_{2}^{d-1} |\sin\varphi|^{d-2} d\varphi dr_{2} dr_{1}$$
$$= \frac{4\pi}{(r^{d}\kappa_{d})^{2}} \frac{\omega_{d-1}\omega_{d}}{\omega_{1}\omega_{2}} \int_{0}^{r} \int_{0}^{r} \int_{0}^{\varphi(r_{1},r_{2})} r_{1}^{d-1} r_{2}^{d-1} \sin^{d-2}\varphi d\varphi dr_{2} dr_{1}$$
$$= \frac{\omega_{d-1}\omega_{d}}{(r^{d}\kappa_{d})^{2}} \int_{0}^{r} \int_{0}^{r} \int_{0}^{\varphi(r_{1},r_{2})} r_{1}^{d-1} r_{2}^{d-1} \sin^{d-2}\varphi d\varphi dr_{2} dr_{1}.$$

The above integral can be evaluated for any specific value of d using multiple integration by parts. In particular,

$$P(2, r, 2) = \frac{4}{\pi r^4} \int_0^r \int_0^r \int_0^{\varphi(r_1, r_2)} r_2 r_1 d\varphi dr_2 dr_1$$

= $\frac{4}{\pi r^4} \int_0^r \int_0^r r_2 r_1 (\arcsin(r_1/2) + \arcsin(r_2/2)) dr_2 dr_1$
= $\frac{4}{\pi r^4} \left(\frac{r^2}{4} (r\sqrt{4 - r^2} + 2(r^2 - 2) \arcsin(r/2)) \right)$
= $\frac{1}{\pi r^2} \left(r\sqrt{4 - r^2} + 2(r^2 - 2) \arcsin(r/2) \right),$ (2.3)

and

$$P(3, r, 2) = \frac{9}{2r^6} \int_0^r \int_0^r \int_0^{\varphi(r_1, r_2)} r_2^2 r_1^2 \sin \varphi \, d\varphi dr_2 dr_1$$

= $\frac{9}{2r^6} \left(\frac{r^2}{288} (-72 + 90r^2 - 4r^4 + 9r^6) + \frac{1}{4} \arcsin(r/2) (R\sqrt{4 - r^2}(r^2 - 2) + 4 \arcsin(r/2)) \right).$

In particular,

$$P(2,1,2) = \frac{\sqrt{3}}{\pi} - \frac{1}{3} = 0.2179...,$$

$$P(3,1,2) = \frac{1}{64}(23 + 12\sqrt{3}\pi - 8\pi^2) = 0.1459...$$

This finishes the proof of Theorem 1.1.

We conclude this section with the following statements.

Corollary 2.1. For any fixed $d \ge 2$, it holds that

$$\lim_{r \to 0^+} P(d, r, 2) = 0.$$

Furthermore, for any fixed $0 < r \leq 1$, it holds that

$$\lim_{d \to \infty} P(d, r, 2) = 0.$$

Proof. Note that, using $\arcsin x \leq \pi x/2$ for $x \in [0, \pi/2]$ and $\sin x \leq x$ for $x \in [0, \pi/2]$, we get that

$$\begin{split} P(d,r,2) &\leq \frac{C(d)}{r^{2d}} \int_0^r \int_0^r \int_0^{r_1+r_2} r_1^{d-1} r_2^{d-1} (r_1+r_2)^{d-2} \, d\varphi dr_2 dr_1 \\ &\leq \frac{2^{d-1}C(d)}{r^{2d}} \int_0^r \int_{r_1}^r \int_0^{2r_2} r_2^{3d-4} \, d\varphi dr_2 dr_1 \\ &= \frac{2^d C(d)}{r^{2d}} \int_0^r \int_0^r r_2^{3d-3} \, dr_2 dr_1 \\ &= \frac{2^d C(d)}{r^{2d}} \frac{r^{3d-1}}{3d-2}, \end{split}$$

where the constant C(d) depends only on the dimension d. From this it follows that

$$\lim_{r \to 0^+} P(d, r, 2) = 0$$

for $d \geq 2$, as claimed.

In the proof of the second statement we use the fact that $\varphi(r_1, r_2) \leq \pi/3$. Thus

$$P(d, r, 2) \leq \frac{\omega_{d-1}\omega_d}{r^{2d}\kappa_d^2} \int_0^r \int_0^r r_1^{d-1} r_2^{d-1} \left(\frac{\sqrt{3}}{2}\right)^{d-1} dr_2 dr_1$$
$$= \frac{\omega_{d-1}\omega_d}{d^2\kappa_d^2} \left(\frac{\sqrt{3}}{2}\right)^{d-1} = \frac{d-1}{d} \frac{\kappa_{d-1}}{\kappa_d} \left(\frac{\sqrt{3}}{2}\right)^{d-1}.$$

From $\kappa_{d-1}/\kappa_d \sim c \cdot \sqrt{d}$ as $d \to \infty$, it follows that $P(d,r,2) \to 0$ as $d \to \infty$.

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3. Proof of Theorem 1.2

The case when n = 3, can be treated, at least in the plane, as follows. We only consider when r = 1, that is, $K = B^2$. Let x_1, x_2, x_3 be i.i.d. uniform random points from B^2 . Let

$$P(2,1,3) := \mathbb{P}(o \in [x_1, x_2, x_3]_1)$$

= $\mathbb{P}(o \in [x_1, x_2]_1) + \mathbb{P}(o \notin [x_1, x_2]_1 \text{ and } o \in [x_1, x_2, x_3]_1)$
= $P(2,1,2) + \mathbb{P}(o \notin [x_1, x_2]_1 \text{ and } o \in [x_1, x_2, x_3]_1).$

Let

$$\overline{P}(2,1,3) := \mathbb{P}(o \notin [x_1, x_2]_1 \text{ and } o \in [x_1, x_2, x_3]_1).$$

Due to the rotational symmetry of B^2 , we may assume that $x_1 = (0, r_1)$. Let $x_2 = r_2 u_2$, where φ is the angle of u_2 and the negative half of the *y*-axis. Making use of the previously introduced notation, we write $K(x_1) = K(1, x_1)$ and, similarly, $K(x_2) = K(1, x_2)$. The ray ox_i divides $K(x_i)$ into two congruent parts. The part that is on the positive side of ox_i is denoted by $K^+(x_i)$, and the negative part is $K^-(x_i)$, as shown in Fig. 2.



FIGURE 2. The regions $K^{-}(x_2)$ and $K^{+}(x_1)$

Let $V^+(x_i) = V_2(K^+(x_i))$ and $V^-(x_i) = V_2(K^-(x_i))$ for i = 1, 2. Then it holds that

$$V^{+}(x_{i}) = V^{-}(x_{i}) = \int_{0}^{1} \int_{0}^{\varphi(r_{i},r)} r \, d\varphi dr = \int_{0}^{1} (\arcsin(r_{i}/2) + \arcsin(r/2)) r \, dr$$
$$= \frac{1}{12} \left(3\sqrt{3} - \pi + 6 \arcsin(r_{i}/2) \right).$$

We distinguish four cases according to the relative position of x_1 and x_2 . Case 1. $r_2 \leq r_1$ and $x_2 \notin [x_1, o]_1$. In this case, $\varphi \in [\varphi(r_1, r_2), \pi - \arcsin(r_1/2) + \arcsin(r_2/2)]$. Then

$$P_{1} := \mathbb{P}(o \notin [x_{1}, x_{2}]_{1} \text{ and } o \in [x_{1}, x_{2}, x_{3}]_{1} \text{ and } x_{2} \notin [x_{1}, o]_{1} \text{ and } r_{1} \ge r_{2})$$

$$= \frac{2\pi}{\pi^{3}} \int_{0}^{1} \int_{0}^{r_{1}} \int_{\varphi(r_{1}, r_{2})}^{\pi - \arcsin(r_{1}/2) + \arcsin(r_{2}/2)} \times \left(V^{+}(x_{1}) + V^{-}(x_{2}) + \frac{\pi - \varphi}{2} \right) r_{1} r_{2} d\varphi dr_{2} dr_{1}$$

$$= \frac{1}{\pi^{2}} \int_{0}^{1} \int_{0}^{r_{1}} \int_{\varphi(r_{1}, r_{2})}^{\pi - \arcsin(r_{1}/2) + \arcsin(r_{2}/2)} \left(\sqrt{3} - \frac{\pi}{3} + \arcsin(r_{1}/2) + \arcsin(r_{2}/2) + \frac{\pi - \varphi}{2} \right) r_{1} r_{2} d\varphi dr_{2} dr_{1}$$

$$= -\frac{5}{72} - \frac{1}{\pi^{2}} + \frac{5}{4\sqrt{3}\pi}.$$

Case 2. $r_2 \ge r_1$ and $x_1 \notin [x_2, o]_1$. By the symmetry of x_1 and x_2 ,

$$P_2 := \mathbb{P}(o \notin [x_1, x_2]_1 \text{ and } o \in [x_1, x_2, x_3]_1 \text{ and } x_1 \notin [x_2, o]_1 \text{ and } r_1 \le r_2)$$
$$= \mathbb{P}(o \notin [x_1, x_2]_1 \text{ and } o \in [x_1, x_2, x_3]_1 \text{ and } x_2 \notin [x_1, o]_1 \text{ and } r_1 \ge r_2)$$
$$= -\frac{5}{72} - \frac{1}{\pi^2} + \frac{5}{4\sqrt{3}\pi}.$$

Case 3. $x_2 \in [x_1, o]_1$.

In this case $r_1 \ge r_2$ and $\varphi \in [\pi - \arcsin(r_1/2) + \arcsin(r_2/2), \pi]$. Then $K(x_2) \subset K(x_1)$, thus

$$P_{3} := \mathbb{P}(o \notin [x_{1}, x_{2}]_{1} \text{ and } o \in [x_{1}, x_{2}, x_{3}]_{1} \text{ and } x_{2} \in [x_{1}, o]_{1})$$

$$= \frac{2\pi}{\pi^{3}} \int_{0}^{1} \int_{0}^{r_{1}} \int_{\pi-\arcsin(r_{1}/2)+\arcsin(r_{2}/2)}^{\pi} V(x_{1})r_{1}r_{2}d\varphi dr_{2}dr_{1}$$

$$= \frac{1}{\pi^{2}} \int_{0}^{1} \int_{0}^{r_{1}} \int_{\pi-\arcsin(r_{1}/2)+\arcsin(r_{2}/2)}^{\pi} \left(\frac{\sqrt{3}}{2} - \frac{\pi}{6} + \arcsin(r_{1}/2)\right)r_{1}r_{2}d\varphi dr_{2}dr_{1}$$

$$= \frac{99 - 24\sqrt{3}\pi + 4\pi^{2}}{576\pi^{2}}.$$

Case 4. $x_1 \in [x_2, o]_1$. Again, by the symmetry of x_1 and x_2 , $P_4 = \mathbb{P}(o \notin [x_1, x_2]_1 \text{ and } o \in [x_1, x_2, x_3]_1 \text{ and } x_1 \in [x_2, o]_1)$ $= \mathbb{P}(o \notin [x_1, x_2]_1 \text{ and } o \in [x_1, x_2, x_3]_1 \text{ and } x_2 \in [x_1, o]_1)$ $= \frac{99 - 24\sqrt{3\pi} + 4\pi^2}{576\pi^2}.$

Thus, considering the symmetry with respect to the line ox_1 , we obtain that

$$\overline{P}(2,1,3) = 2(P_1 + P_2 + P_3 + P_4) = \frac{-36\pi^2 - 477 + 216\sqrt{3\pi}}{144\pi^2}.$$

Thus,

$$P(2,1,3) = P(2,1,2) + \overline{P}(2,1,3) = \frac{-84\pi^2 - 477 + 360\sqrt{3}\pi}{144\pi^2} = 0.4594\dots$$

We note that the actual calculation can be carried out, at least numerically, for any $0 < r \leq 1$. Furthermore, the cases of $n = 4, 5, \ldots$ are essentially similar, although the case analysis grows significantly more complicated as n increases.

Finally, we note that according to Wendel's equality (1.1),

$$\mathbb{P}(0 \in [x_1, x_2, x_3]) = \frac{1}{4} < P(2, 1, 3).$$

4. The case of normally distributed random points

In this subsection we consider the model in which $\rho = 1$ and x_1, \ldots, x_n are i.i.d. random points in \mathbb{R}^d that are distributed according to the standard normal distribution with density function

$$f(x) = \frac{1}{(2\pi)^{\frac{d}{2}}} e^{-\frac{|x|^2}{2}}, \ x \in \mathbb{R}^d.$$

Here we need to use the part of the definition of the spindle convex hull that normally does not come into play when the random points are chosen from a convex body that is spindle convex with radius less than or equal to 1. Namely, if $x, y \in \mathbb{R}^d$ are such that |x - y| > 2, then $[x, y]_1 := \mathbb{R}^d$.

We are interested in the following probability

$$P_N(d,1,n) := \mathbb{P}(o \in [x_1,\ldots,x_n]_1).$$

It is clear that

$$\mathbb{P}(o \in [x_1, \dots, x_n]) \le \mathbb{P}(o \in [x_1, \dots, x_n]_1)$$

as $[X] \subset [X]_1$ for any $X \subset \mathbb{R}^d$.

Let E be the event that $|x_1 - x_2| \leq 2$. Then

$$P_N(d, 1, 2) = \mathbb{P}(o \in [x_1, x_2]_1 \text{ and } E) + \mathbb{P}(E^c),$$

where E^c is the complement of E, as E^c automatically implies that $o \in [x_1, x_2]_1$.

Let *l* denote the length of the random segment $[x_1x_2]$. It is known (see [5, p. 438] and the historical references therein) that the density of $s := l^2/4$ is

$$g(s) = \frac{s^{\frac{d}{2}-1}e^{-s}}{\Gamma(d/2)}, \ 0 < s < \infty.$$
(4.1)

Thus,

$$\mathbb{P}(E^c) = \int_1^\infty g(s) \, ds = \frac{\gamma(d/2, 1)}{\Gamma(d/2)},$$

where $\Gamma(\cdot)$ is Euler's gamma function, and $\gamma(d/2, x)$ denotes the lower incomplete gamma function.

Using the linear Blaschke–Petkantschin formula (2.2) and the rotational invariance of the standard normal distribution we obtain that

$$\mathbb{P}(o \in [x_1, x_2]_1 \text{ and } E)$$

$$= \frac{1}{(2\pi)^d} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} \mathbf{1}(o \in [x_1, x_2]_1 \text{ and } E) e^{-\frac{|x_1|^2 + |x_2|^2}{2}} dx_1 dx_2$$

$$= \frac{1}{(2\pi)^d} \frac{\omega_{d-1}\omega_d}{\omega_1 \omega_2} \int_{G(d,2)} \int_{L^2} \mathbf{1}(o \in [x_1, x_2]_1 \text{ and } E)$$

$$\times \Delta^{d-2}(x_1, x_2) e^{-\frac{|x_1|^2 + |x_2|^2}{2}} dx_1 dx_2 \nu_2 (dL)$$

$$= \frac{1}{(2\pi)^d} \frac{\omega_{d-1}\omega_d}{\omega_1 \omega_2} \int_{L^2} \mathbf{1}(o \in [x_1, x_2]_1 \text{ and } E) \Delta^{d-2}(x_1, x_2) e^{-\frac{|x_1|^2 + |x_2|^2}{2}} dx_1 dx_2.$$

In order to evaluate the above integral, we use polar coordinates $x_1 = r_1 u_1$ and $x_2 = r_2 u_2$, $r_1, r_2 \ge 0$, $u_1, u_2 \in S^1$. Let φ be the angle of $-u_1$ and u_2 , as before. For $2 - r_1 \le r_2 \le \sqrt{4 - r_1^2}$, let

$$\psi(r_1, r_2) = \pi - \arccos\left(\frac{r_1^2 + r_2^2 - 4}{2r_1r_2}\right)$$

We distinguish two cases according to r_2 . When $0 \leq r_2 \leq 2 - r_1$, then $-\varphi(r_1, r_2) \leq \varphi \leq \varphi(r_1, r_2)$, and when $2 - r_1 \leq r_2 \leq \sqrt{4 - r_1^2}$, then $-\varphi(r_1, r_2) \leq \varphi \leq -\psi(r_1, r_2)$ and $\psi(r_1, r_2) \leq \varphi(r_1, r_2)$, see Fig. 3.

By the rotational symmetry of the normal distribution, integration with respect to u_1 is just a multiplication by 2π . Then, w obtain that

$$\mathbb{P}(o \in [x_1, x_2]_1 \text{ and } E)$$

$$=\frac{2}{(2\pi)^{d-1}}\frac{\omega_{d-1}\omega_d}{\omega_1\omega_2}\int_0^2\int_0^{2-r_1}\int_0^{\varphi(r_1,r_2)}r_1^{d-1}r_2^{d-1}\sin^{d-2}(\varphi)\,e^{-\frac{r_1^2+r_2^2}{2}}d\varphi dr_2dr_1^{d-1}d\varphi$$



FIGURE 3. Integration bounds in φ according to r_2

$$+ \frac{2}{(2\pi)^{d-1}} \frac{\omega_{d-1}\omega_d}{\omega_1\omega_2} \int_0^2 \int_{2-r_1}^{\sqrt{4-r_1^2}} \int_{\psi(r_1,r_2)}^{\varphi(r_1,r_2)} r_1^{d-1} r_2^{d-1} \times \sin^{d-2}(\varphi) e^{-\frac{r_1^2+r_2^2}{2}} d\varphi dr_2 dr_1.$$

The above integrals can be evaluated, at least numerically, for any specific value of d. In particular, for d = 2, we obtain for the first integral

$$\frac{1}{\pi} \int_0^2 \int_0^{2-r_1} \int_0^{\varphi(r_1, r_2)} r_1 r_2 \, e^{-\frac{r_1^2 + r_2^2}{2}} \, d\varphi dr_2 dr_1$$

= $\frac{1}{\pi} \int_0^2 \int_0^{2-r_1} (\arcsin(r_1/2) + \arcsin(r_2/2)) r_1 r_2 \, e^{-\frac{r_1^2 + r_2^2}{2}} \, dr_2 dr_1$
= 0.079214....

The second integral is

$$\frac{1}{\pi} \int_0^2 \int_{2-r_1}^{\sqrt{4-r_1^1}} \int_{\psi(r_1,r_2)}^{\varphi(r_1,r_2)} r_1 r_2 \, e^{-\frac{r_1^2 + r_2^2}{2}} \, d\varphi dr_2 dr_1$$
$$= \frac{1}{\pi} \int_0^2 \int_{2-r_1}^{\sqrt{4-r_1^2}} \left(\arcsin(r_1/2) + \arcsin(r_2/2) - \pi + \arccos\left(\frac{r_1^2 + r_2^2 - 4}{2r_1 r_2}\right) \right)$$

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×
$$r_1 r_2 e^{-\frac{r_1^2 + r_2^2}{2}} dr_2 dr_1$$

= 0.01866....
For $d = 2$,
 $\mathbb{P}(E^c) = \frac{\gamma(1,1)}{\Gamma(1)} = \frac{1}{e} = 0.367879...,$ thus, in summary,
 $P_N(2,1,2) = 0.465753....$

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Declarations

Conflict of interest The authors have no relevant financial or non-financial interests to disclose.

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