Characterizations of balls by sections and caps

Árpád Kurusa and Tibor Ódor

Abstract. Among others, we prove that if a convex body \mathcal{K} and a ball \mathcal{B} have equal constant volumes of caps and equal constant areas of sections with respect to the supporting planes of a sphere, then $\mathcal{K} \equiv \mathcal{B}$.

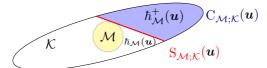
1 Introduction

If the convex body \mathcal{M} , the *kernel*, contains the origin O, let $\hbar_{\mathcal{M}}(\boldsymbol{u})$ denote the supporting hyperplane of \mathcal{M} that is perpendicular to the unit vector $\boldsymbol{u} \in \mathbb{S}^{n-1}$ and contains in its same half space $\hbar_{\mathcal{M}}^{-}(\boldsymbol{u})$ the origin O and the kernel \mathcal{M} . Its other half space is denoted by $\hbar_{\mathcal{M}}^{+}(\boldsymbol{u})$.

If the convex body ${\mathcal K}$ contains the kernel ${\mathcal M}$ in its interior, we define the functions

- (1.1) $S_{\mathcal{M};\mathcal{K}}(\boldsymbol{u}) = |\mathcal{K} \cap \hbar_{\mathcal{M}}(\boldsymbol{u})|,$ (section function¹)
- (1.2) $C_{\mathcal{M};\mathcal{K}}(\boldsymbol{u}) = |\mathcal{K} \cap \hbar^+_{\mathcal{M}}(\boldsymbol{u})|, \qquad (cap function)$

where $|\cdot|$ is the appropriate Lebesgue measure.



The goal of this article is to investigate the problem of determining \mathcal{K} if some functions of the form (1.1) and (1.2) are given for a kernel \mathcal{M} .

AMS Subject Classification (2012): 52A40.

¹This is usually called *chord function* in the plane.

Key words and phrases: sections, caps, ball, sphere, characterization, isoperimetric inequality, floating body.

Two convex bodies \mathcal{K} and \mathcal{K}' are called \mathcal{M} -equicapped if $C_{\mathcal{M};\mathcal{K}} \equiv C_{\mathcal{M};\mathcal{K}'}$, and they are \mathcal{M} -equisectioned if $S_{\mathcal{M};\mathcal{K}} \equiv S_{\mathcal{M};\mathcal{K}'}$. A convex body \mathcal{K} is called \mathcal{M} -isocapped if $C_{\mathcal{M};\mathcal{K}}$ is constant. It is said to be \mathcal{M} -isosectioned if $S_{\mathcal{M};\mathcal{K}}$ is constant.

First we prove in the plane that

- (a) two convex bodies coincide if they are \mathcal{M} -equicapped and \mathcal{M} -equisectioned, no matter what \mathcal{M} is (Theorem 3.1), and
- (b) any disc-isocapped convex body is a disc concentric to the kernel (Theorem 3.2^2).

Then, in higher dimensions we consider only such convex bodies that are sphereequisectioned and sphere-equicapped with a ball, and prove that

- a convex body that is sphere-equicapped and sphere-equisectioned with a ball, is itself a ball (Theorem 5.3);
- (2) a convex body that is twice sphere-equicapped (for two different concentric spheres) with a ball is itself a ball (Theorem 5.1);
- (3) a convex body that is twice sphere-equisectioned (for two different concentric spheres) with a ball is itself a ball (Theorem 5.2, but dimension n = 3 excluded).

For more information about the subject we refer the reader to [1,3] etc.

2 Preliminaries

We work with the *n*-dimensional real space \mathbb{R}^n , its unit ball is $\mathcal{B} = \mathcal{B}^n$ (in the plane the unit disc is \mathcal{D}), its unit sphere is \mathbb{S}^{n-1} and the set of its hyperplanes is \mathbb{H} . The ball (resp. disc) of radius $\varrho > 0$ centred to the origin is denoted by $\varrho \mathcal{B} = \varrho \mathcal{B}^n$ (resp. $\varrho \mathcal{D}$).

Using the spherical coordinates $\boldsymbol{\xi} = (\xi_1, \ldots, \xi_{n-1})$ every unit vector can be written in the form $\boldsymbol{u}_{\boldsymbol{\xi}} = (\cos \xi_1, \sin \xi_1 \cos \xi_2, \sin \xi_1 \sin \xi_2 \cos \xi_3, \ldots)$, the *i*-th coordinate of which is $u_{\boldsymbol{\xi}}^i = (\prod_{j=1}^{i-1} \sin \xi_j) \cos \xi_i$ ($\xi_n := 0$). In the plane we even use the $\boldsymbol{u}_{\boldsymbol{\xi}} = (\cos \xi, \sin \xi)$ and $\boldsymbol{u}_{\boldsymbol{\xi}}^{\perp} = \boldsymbol{u}_{\boldsymbol{\xi}+\pi/2} = (-\sin \xi, \cos \xi)$ notations and in analogy to this latter one, we introduce the notation $\boldsymbol{\xi}^{\perp} = (\xi_1, \ldots, \xi_{n-2}, \xi_{n-1} + \pi/2)$ for higher dimensions.

A hyperplane $\hbar \in \mathbb{H}$ is parametrized so that $\hbar(\boldsymbol{u}_{\boldsymbol{\xi}}, r)$ means the one that is orthogonal to the unit vector $\boldsymbol{u}_{\boldsymbol{\xi}} \in \mathbb{S}^{n-1}$ and contains the point $r\boldsymbol{u}_{\boldsymbol{\xi}}$, where $r \in \mathbb{R}^3$. For convenience we also frequently use $\hbar(P, \boldsymbol{u}_{\boldsymbol{\xi}})$ to denote the hyperplane through the point $P \in \mathbb{R}^n$ with normal vector $\boldsymbol{u}_{\boldsymbol{\xi}} \in \mathbb{S}^{n-1}$. For instance, $\hbar(P, \boldsymbol{u}_{\boldsymbol{\xi}}) =$ $\hbar(\boldsymbol{u}_{\boldsymbol{\xi}}, \langle \overrightarrow{OP}, \boldsymbol{u}_{\boldsymbol{\xi}} \rangle)$, where $O = \mathbf{0}$ is the origin and $\langle ., . \rangle$ is the usual inner product.

 $^{^{2}}$ [1, Theorem 1] gives the same conclusion in the plane for disc-isosectioned convex bodies.

³Athough $\hbar(\boldsymbol{u}_{\boldsymbol{\xi}}, r) = \hbar(-\boldsymbol{u}_{\boldsymbol{\xi}}, -r)$ this parametrization is locally bijective.

On a convex body we mean a convex compact set $\mathcal{K} \subseteq \mathbb{R}^n$ with nonempty interior \mathcal{K}° and with piecewise \mathbb{C}^1 boundary $\partial \mathcal{K}$. For a convex body \mathcal{K} we let $p_{\mathcal{K}} \colon \mathbb{S}^{n-1} \to \mathbb{R}$ denote support function of \mathcal{K} , which is defined by $p_{\mathcal{K}}(\boldsymbol{u}_{\xi}) = \sup_{\boldsymbol{x} \in \mathcal{K}} \langle \boldsymbol{u}_{\xi}, \boldsymbol{x} \rangle$. We also use the notation $\hbar_{\mathcal{K}}(\boldsymbol{u}) = \hbar(\boldsymbol{u}, p_{\mathcal{K}}(\boldsymbol{u}))$. If the origin is in \mathcal{K}° , another useful function of a convex body \mathcal{K} is its radial function $\varrho_{\mathcal{K}} \colon \mathbb{S}^{n-1} \to \mathbb{R}_+$ which is defined by $\varrho_{\mathcal{K}}(\boldsymbol{u}) = |\{r\boldsymbol{u} : r > 0\} \cap \partial \mathcal{K}|$.

We need the special functions $I_x(a, b)$, the regularized incomplete beta function, B(x; a, b), the incomplete beta function, B(a, b), the beta function, and $\Gamma(y)$, Euler's Gamma function, where $0 < a, b \in \mathbb{R}$, $x \in [0, 1]$ and $y \in \mathbb{R}$. We introduce finally the notation $|\mathbb{S}^k| := 2\pi^{k/2}/\Gamma(k/2)$ as the standard surface measure of the k-dimensional sphere. For the special functions we refer the reader to [11, 12].

We shall frequently use the utility function χ that takes relations as argument and gives 1 if its argument fulfilled. For example $\chi(1 > 0) = 1$, but $\chi(1 \le 0) = 0$ and $\chi(x > y)$ is 1 if x > y and it is zero if $x \le y$. Nevertheless we still use χ also as the indicator function of the set given in its subscript.

A strictly positive integrable function $\omega \colon \mathbb{R}^n \setminus \mathcal{B} \to \mathbb{R}_+$ is called *weight* and the integral

$$V_{\omega}(f) := \int_{\mathbb{R}^n \setminus \mathcal{B}} f(x) \omega(x) dx$$

of an integrable function $f \colon \mathbb{R}^n \to \mathbb{R}$ is called the volume of f with respect to the weight ω or simply the ω -volume of f. For the volume of the indicator function $\chi_{\mathcal{S}}$ of a set $\mathcal{S} \subseteq \mathbb{R}^n$ we use the notation $V_{\omega}(\mathcal{S}) := V_{\omega}(\chi_{\mathcal{S}})$ as a shorthand. If more weights are indexed by $i \in \mathbb{N}$, then we use the even shorter notation $V_i(\mathcal{S}) := V_{\omega_i}(\mathcal{S}) = V_i(\chi_{\mathcal{S}}) := V_{\omega_i}(\chi_{\mathcal{S}}).$

3 In the plane

We heard the following easy result from Kincses [5].

Theorem 3.1. Assume that the border of the strictly convex plane bodies \mathcal{M} and \mathcal{K} are differentiable of class C^1 and we are given \mathcal{M} and the functions $S_{\mathcal{M};\mathcal{K}}$ and $C_{\mathcal{M};\mathcal{K}}$. Then \mathcal{K} can be uniquely determined.

Proof. Fix the origin **0** in \mathcal{M}° . In the plane $u_{\xi} = (\cos \xi, \sin \xi)$, therefore we consider the functions

$$f(\xi) := S_{\mathcal{M};\mathcal{K}}(\boldsymbol{u}_{\xi}) = |\hbar(p_{\mathcal{M}}(\boldsymbol{u}_{\xi}), \boldsymbol{u}_{\xi}) \cap \mathcal{K}|$$
$$g(\xi) := C_{\mathcal{M};\mathcal{K}}(\boldsymbol{u}_{\xi}) = |\hbar^{+}(p_{\mathcal{M}}(\boldsymbol{u}_{\xi}), \boldsymbol{u}_{\xi}) \cap \mathcal{K}$$

where \hbar^+ is the appropriate halfplane bordered by \hbar .

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Let $\boldsymbol{h}(\xi)$ be the point, where $\hbar(p_{\mathcal{M}}(\xi), \boldsymbol{u}_{\xi})$ touches \mathcal{M} . Then, as it is well known, $\boldsymbol{h}(\xi) - p_{\mathcal{M}}(\xi)\boldsymbol{u}_{\xi} = p'_{\mathcal{M}}(\xi)\boldsymbol{u}_{\xi}^{\perp}$. Let $\boldsymbol{a}(\xi)$ and $\boldsymbol{b}(\xi)$ be the two intersections of $\hbar(p_{\mathcal{M}}(\xi), \boldsymbol{u}_{\xi})$ and $\partial \mathcal{K}$ taken so that $\boldsymbol{a}(\xi) = \boldsymbol{h}(\xi) + \boldsymbol{a}(\xi)\boldsymbol{u}_{\xi}^{\perp}$ and $\boldsymbol{b}(\xi) = \boldsymbol{h}(\xi) - \boldsymbol{b}(\xi)\boldsymbol{u}_{\xi}^{\perp}$, where $\boldsymbol{a}(\xi)$ and $\boldsymbol{b}(\xi)$ are positive functions.

Then $f(\xi) = a(\xi) + b(\xi)$.

In the other hand, we have

$$g(\xi) = \int_{\mathcal{K}\setminus\mathcal{M}} \chi(\langle \boldsymbol{x}, \boldsymbol{u}_{\xi} \rangle \ge p_{\mathcal{M}}(\xi)) \, d\boldsymbol{x} = \int_{-\pi/2}^{\pi/2} \int_{0}^{\varrho_{\xi}(\zeta)} r \, dr \, d\zeta,$$

where $h(\xi) + \varrho_{\xi}(\zeta)u_{\zeta} \in \partial \mathcal{K}$. Since $\frac{d\varrho_{\xi}(\zeta)}{d\xi} = \frac{d\varrho_{\xi}(\zeta)}{d\zeta}$, this leads to

$$2g'(\xi) = \int_{-\pi/2}^{\pi/2} \frac{d}{d\xi} \Big(\int_0^{\varrho_{\xi}(\zeta)} 2r \, dr \Big) \, d\zeta = \int_{-\pi/2}^{\pi/2} 2\varrho_{\xi}(\zeta) \varrho_{\xi}'(\zeta) \, d\zeta = a^2(\xi) - b^2(\xi)$$

that implies

$$a(\xi) = \frac{\frac{2g'(\xi)}{f(\xi)} + f(\xi)}{2} = \frac{2g'(\xi) + f^2(\xi)}{2f(\xi)}.$$

This clearly determines \mathcal{K} .

If the kernel \mathcal{M} is known to be a disc $\rho \mathcal{D}$, then any one of the functions $S_{\rho \mathcal{D};\mathcal{K}}$ and $C_{\rho \mathcal{D};\mathcal{K}}$ can determine concentric discs by its constant value.

Theorem 3.2. Assume that one of the functions $S_{\varrho \mathcal{D};\mathcal{K}}$ and $C_{\varrho \mathcal{D};\mathcal{K}}$ is constant, where \mathcal{D} is the unit disc. Then \mathcal{K} is a disc centred to the origin.

Proof. If $S_{\rho \mathcal{D};\mathcal{K}}$ is constant, then this theorem is [1, Theorem 1].

If $C_{\varrho \mathcal{D};\mathcal{K}}$ is constant, the derivative of $C_{\varrho \mathcal{D};\mathcal{K}}$ is zero, hence —using the notations of the previous proof— $a(\xi) = \underline{b}(\xi)$ for every $\xi \in [0, 2\pi)$, that is, the point $h(\xi)$ is the midpoint of the segment $\overline{a(\xi)b(\xi)}$ on $\hbar(\varrho, u_{\xi})$.

Let us consider the chord-map $C: \partial \mathcal{K} \to \partial \mathcal{K}$, that is defined by $C(\mathbf{b}(\xi)) = \mathbf{a}(\xi)$ for every $\xi \in [0, 2\pi)$. This is clearly a bijective map. If $\boldsymbol{\ell}_0 \in \partial \mathcal{K}$, then by $a(\xi) = b(\xi)$ the whole sequence $\boldsymbol{\ell}_i = C^i(\boldsymbol{\ell})$, where C^i means the *i* consecutive usage of *C*, are on a concentric circle of radius $|\boldsymbol{\ell}_0|$. Moreover, every point $\boldsymbol{\ell}_i$ (i > 0) is the concentric rotation of $\boldsymbol{\ell}_{i-1}$ with angle $\lambda = 2 \arccos(\varrho/|\boldsymbol{\ell}_0|)$. It is well known [4, Proposition 1.3.3] that such a sequence is dense in $\partial \mathcal{K}$ if λ/π is irrational, or it is finitely periodic in $\partial \mathcal{K}$ if λ/π is rational. However, if \mathcal{K} is not a disc, then there is surely a point $\boldsymbol{\ell} \in \partial \mathcal{K}$ for which $2 \arccos(\varrho/|\boldsymbol{\ell}_0|)/\pi$ is irrational, hence \mathcal{K} must be a concentric disc.

4 Measures of convex bodies

In this section the dimension of the space is n = 2, 3, ... As a shorthand we introduce the notations

(4.1)
$$S_{\varrho;\mathcal{K}}(\boldsymbol{u}) := S_{\varrho\mathcal{B};\mathcal{K}}(\hbar(\varrho,\boldsymbol{u})) = |\mathcal{K} \cap \hbar(\varrho,\boldsymbol{u})|,$$

(4.2)
$$C_{\varrho;\mathcal{K}}(\boldsymbol{u}) := C_{\varrho\mathcal{B};\mathcal{K}}(\hbar(\varrho,\boldsymbol{u})) = |\mathcal{K} \cap \hbar^+(\varrho,\boldsymbol{u})|,$$

where $\rho \mathcal{B}^n$ is the ball of radius $\rho > 0$ centred to the origin and \hbar^+ is the appropriate halfspace bordered by \hbar .

Lemma 4.1. If the convex body \mathcal{K} in \mathbb{R}^n contains in its interior the ball $\varrho \mathcal{B}^n$, then

(4.3)
$$\int_{\mathbb{S}^{n-1}} \mathcal{C}_{\varrho;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}}) d\boldsymbol{\xi} = \frac{\pi^{n/2}}{\Gamma(n/2)} \int_{\mathcal{K}\setminus\varrho\mathcal{B}} I_{1-\frac{\varrho^2}{|\boldsymbol{x}|^2}}\left(\frac{n-1}{2},\frac{1}{2}\right) d\boldsymbol{x},$$

Proof. We have

$$\begin{split} \int_{\mathbb{S}^{n-1}} \mathcal{C}_{\varrho;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}}) d\boldsymbol{\xi} &= \int_{\mathbb{S}^{n-1}} \int_{\mathbb{R}^n} \chi_{\mathcal{K}}(\boldsymbol{x}) \chi(\langle \boldsymbol{x}, \boldsymbol{u}_{\boldsymbol{\xi}} \rangle \geq \varrho) \, d\boldsymbol{x} d\boldsymbol{\xi} \\ &= \int_{\mathcal{K} \setminus \varrho \mathcal{B}} \int_{\mathbb{S}^{n-1}} \chi\Big(\Big\langle \frac{\boldsymbol{x}}{|\boldsymbol{x}|}, \boldsymbol{u}_{\boldsymbol{\xi}} \Big\rangle \geq \frac{\varrho}{|\boldsymbol{x}|} \Big) \, d\boldsymbol{\xi} d\boldsymbol{x} \end{split}$$

The inner integral is the surface of the hyperspherical cap. The height of this hyperspherical cap is $h = 1 - \rho/|\mathbf{x}|$, hence by the well-known formula [13] we obtain

$$\int_{\mathbb{S}^{n-1}} \chi\left(\left\langle \frac{\boldsymbol{x}}{|\boldsymbol{x}|}, \boldsymbol{u}_{\boldsymbol{\xi}} \right\rangle \geq \frac{\varrho}{|\boldsymbol{x}|}\right) d\boldsymbol{\xi} = \frac{\pi^{n/2}}{\Gamma(n/2)} I_{\frac{|\boldsymbol{x}|^2 - \varrho^2}{|\boldsymbol{x}|^2}}\left(\frac{n-1}{2}, \frac{1}{2}\right)$$

This proves the lemma.

Note that the weight in (4.3) is $\frac{\pi}{\Gamma(1)}I_{1-\frac{\varrho^2}{|\boldsymbol{x}|^2}}(\frac{1}{2},\frac{1}{2}) = 2 \arccos(\varrho/|\boldsymbol{x}|)$ for dimension n = 2, and it is $\frac{\pi^{3/2}}{\Gamma(3/2)}I_{1-\frac{\varrho^2}{|\boldsymbol{x}|^2}}(1,\frac{1}{2}) = 2\pi(1-\varrho/|\boldsymbol{x}|)$ for dimension n = 3.

Lemma 4.2. Let the convex body \mathcal{K} contain in its interior the ball $\varrho \mathcal{B}^n$. Then the integral of the section function is

(4.4)
$$\int_{\mathbb{S}^{n-1}} \mathcal{S}_{\varrho;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}}) d\boldsymbol{\xi} = |\mathbb{S}^{n-2}| \int_{\mathcal{K} \setminus \varrho \mathcal{B}^n} \frac{(\boldsymbol{x}^2 - \varrho^2)^{\frac{n-3}{2}}}{|\boldsymbol{x}|^{n-2}} d\boldsymbol{x}.$$

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Proof. Observe, that using (4.3) we have for any $\varepsilon > 0$ that

$$\begin{split} \frac{\Gamma(n/2)}{\pi^{n/2}} & \int_{0}^{\varepsilon} \int_{\mathbb{S}^{n-1}} \mathbf{S}_{\varrho+\delta;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}}) d\boldsymbol{\xi} d\delta \\ &= \frac{\Gamma(n/2)}{\pi^{n/2}} \int_{\mathbb{S}^{n-1}} \int_{0}^{\varepsilon} \mathbf{S}_{\varrho+\delta;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}}) d\delta d\boldsymbol{\xi} \\ &= \frac{\Gamma(n/2)}{\pi^{n/2}} \int_{\mathbb{S}^{n-1}} \mathbf{C}_{\varrho;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}}) - \mathbf{C}_{\varrho+\varepsilon;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}}) d\boldsymbol{\xi} \\ &= \int_{\mathcal{K} \setminus \varrho \mathcal{B}} I_{\frac{|\boldsymbol{x}|^{2} - \varrho^{2}}{|\boldsymbol{x}|^{2}}} \left(\frac{n-1}{2}, \frac{1}{2}\right) d\boldsymbol{x} - \int_{\mathcal{K} \setminus (\varrho+\varepsilon)\mathcal{B}} I_{\frac{|\boldsymbol{x}|^{2} - (\varrho+\varepsilon)^{2}}{|\boldsymbol{x}|^{2}}} \left(\frac{n-1}{2}, \frac{1}{2}\right) d\boldsymbol{x} \\ &= \int_{(\varrho+\varepsilon)\mathcal{B} \setminus \varrho \mathcal{B}} I_{\frac{|\boldsymbol{x}|^{2} - \varrho^{2}}{|\boldsymbol{x}|^{2}}} \left(\frac{n-1}{2}, \frac{1}{2}\right) d\boldsymbol{x} - \int_{\mathcal{K} \setminus (\varrho+\varepsilon)\mathcal{B}} I_{\frac{|\boldsymbol{x}|^{2} - (\varrho+\varepsilon)^{2}}{|\boldsymbol{x}|^{2}}} \left(\frac{n-1}{2}, \frac{1}{2}\right) - I_{\frac{|\boldsymbol{x}|^{2} - \varrho^{2}}{|\boldsymbol{x}|^{2}}} \left(\frac{n-1}{2}, \frac{1}{2}\right) d\boldsymbol{x}, \end{split}$$

hence

$$\begin{split} \lim_{\varepsilon \to 0} \frac{1}{\varepsilon} \frac{\Gamma(n/2)}{\pi^{n/2}} \int_{0}^{\varepsilon} \int_{\mathbb{S}^{n-1}} \mathbf{S}_{\varrho+\delta;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}}) d\boldsymbol{\xi} d\delta \\ &= \lim_{\varepsilon \to 0} \frac{1}{\varepsilon} \int_{(\varrho+\varepsilon)\mathcal{B}\setminus \mathcal{Q}\mathcal{B}} I_{\frac{|\boldsymbol{x}|^2 - \varrho^2}{|\boldsymbol{x}|^2}} \left(\frac{n-1}{2}, \frac{1}{2}\right) d\boldsymbol{x} - \\ &- \int_{\mathcal{K}\setminus \mathcal{Q}\mathcal{B}} \lim_{\varepsilon \to 0} \frac{1}{\varepsilon} \left(I_{\frac{|\boldsymbol{x}|^2 - (\varrho+\varepsilon)^2}{|\boldsymbol{x}|^2}} \left(\frac{n-1}{2}, \frac{1}{2}\right) - I_{\frac{|\boldsymbol{x}|^2 - \varrho^2}{|\boldsymbol{x}|^2}} \left(\frac{n-1}{2}, \frac{1}{2}\right)\right) d\boldsymbol{x} \\ &= \lim_{\varepsilon \to 0} \frac{|\mathbb{S}^{n-1}|}{\varepsilon} \int_{\varrho}^{\varrho+\varepsilon} r^{n-1} I_{\frac{r^2 - \varrho^2}{r^2}} \left(\frac{n-1}{2}, \frac{1}{2}\right) dr - \\ &- \int_{\mathcal{K}\setminus \mathcal{Q}\mathcal{B}} \frac{d}{d\varrho} \left(I_{\frac{|\boldsymbol{x}|^2 - \varrho^2}{|\boldsymbol{x}|^2}} \left(\frac{n-1}{2}, \frac{1}{2}\right)\right) d\boldsymbol{x} \\ &= |\mathbb{S}^{n-1}| \varrho^{n-1} I_{\frac{\varrho^2 - \varrho^2}{\varrho^2}} \left(\frac{n-1}{2}, \frac{1}{2}\right) - \\ &- \frac{1}{B(\frac{n-1}{2}, \frac{1}{2})} \int_{\mathcal{K}\setminus \mathcal{Q}\mathcal{B}} \left(1 - \frac{\varrho^2}{|\boldsymbol{x}|^2}\right)^{\frac{n-3}{2}} \left(\frac{\varrho^2}{|\boldsymbol{x}|^2}\right)^{-1/2} \frac{-2\varrho}{|\boldsymbol{x}|^2} d\boldsymbol{x} \\ &= \frac{2}{B(\frac{n-1}{2}, \frac{1}{2})} \int_{\mathcal{K}\setminus \mathcal{Q}\mathcal{B}} \left(1 - \frac{\varrho^2}{|\boldsymbol{x}|^2}\right)^{\frac{n-3}{2}} \frac{1}{|\boldsymbol{x}|} d\boldsymbol{x}. \end{split}$$

 \mathbf{As}

$$\frac{\pi^{n/2}}{\Gamma(n/2)}\frac{2}{B(\frac{n-1}{2},\frac{1}{2})} = \frac{2\pi^{n/2}}{\Gamma(\frac{n-1}{2})\Gamma(\frac{1}{2})} = \frac{\frac{n-1}{2}}{\frac{n-1}{2}}\frac{2\pi^{\frac{n-1}{2}}}{\Gamma(\frac{n-1}{2})} = \frac{(n-1)\pi^{\frac{n-1}{2}}}{\Gamma(\frac{n-1}{2}+1)} = |\mathbb{S}^{n-2}|,$$

the statement is proved.

6

Note that the weight in (4.4) is $\frac{2}{\sqrt{x^2-\varrho^2}}$ in the plane, and $2\pi/|x|$ in dimension n = 3, which is independent from $\varrho!$

A version of the following lemma first appeared in [9].

Lemma 4.3. Let ω_i (i = 1, 2) be weights and let \mathcal{K} and \mathcal{L} be convex bodies containing the unit ball \mathcal{B} . If $V_1(\mathcal{K}) \leq V_1(\mathcal{L})$ and

- (1) either ω_2/ω_1 is a constant $c_{\mathcal{K}}$ on $\partial \mathcal{K}$ and $\frac{\omega_2}{\omega_1}(X) \begin{cases} \geq c_{\mathcal{K}}, & \text{if } X \notin \mathcal{K}, \\ \leq c_{\mathcal{K}}, & \text{if } X \in \mathcal{K}, \end{cases}$ where equality may occur in a set of measure zero at most,
- (2) or ω_2/ω_1 is a constant $c_{\mathcal{L}}$ on $\partial \mathcal{L}$ and $\frac{\omega_2}{\omega_1}(X) \begin{cases} \leq c_{\mathcal{L}}, & \text{if } X \notin \mathcal{L}, \\ \geq c_{\mathcal{L}}, & \text{if } X \in \mathcal{L}, \end{cases}$ where equality may occur in a set of measure zero at most,

then $V_2(\mathcal{K}) \leq V_2(\mathcal{L})$, where equality is if and only if $\mathcal{K} = \mathcal{L}$.

Proof. We have

$$\begin{aligned} V_{2}(\mathcal{L}) - V_{2}(\mathcal{K}) \\ &= V_{2}(\mathcal{L} \setminus \mathcal{K}) - V_{2}(\mathcal{K} \setminus \mathcal{L}) = \int_{\mathcal{L} \setminus \mathcal{K}} \frac{\omega_{2}(x)}{\omega_{1}(x)} \omega_{1}(x) dx - \int_{\mathcal{K} \setminus \mathcal{L}} \frac{\omega_{2}(x)}{\omega_{1}(x)} \omega_{1}(x) dx \\ \begin{cases} = 0, & \text{if } \mathcal{K} \triangle \mathcal{L} = \emptyset, \\ > c_{\mathcal{K}}(V_{1}(\mathcal{L} \setminus \mathcal{K}) - V_{1}(\mathcal{K} \setminus \mathcal{L})) = c_{\mathcal{K}}(V_{1}(\mathcal{L}) - V_{1}(\mathcal{K})), & \text{if } \mathcal{K} \triangle \mathcal{L} \neq \emptyset \text{ and } (1), \\ > c_{\mathcal{L}}(V_{1}(\mathcal{L} \setminus \mathcal{K}) - V_{1}(\mathcal{K} \setminus \mathcal{L})) = c_{\mathcal{L}}(V_{1}(\mathcal{L}) - V_{1}(\mathcal{K})), & \text{if } \mathcal{K} \triangle \mathcal{L} \neq \emptyset \text{ and } (2), \end{cases} \end{aligned}$$

that proves the theorem.

5 Ball characterizations

Although the following results are valid also in the plane, their points are for higher dimensions.

Theorem 5.1. Let $0 < \varrho_1 < \varrho_2 < \bar{r}$ and let \mathcal{K} be a convex body having $\varrho_2 \mathcal{B}$ in its interior. If $C_{\varrho_1;\mathcal{K}} = C_{\varrho_1;\bar{r}\mathcal{B}}$ and $C_{\varrho_2;\mathcal{K}} = C_{\varrho_2;\bar{r}\mathcal{B}}$, then $\mathcal{K} \equiv \bar{r}\mathcal{B}$, where \mathcal{B} is the unit ball.

Proof. Let $\bar{\omega}_1(r) = I_{\frac{r^2-\varrho_1^2}{r^2}}(\frac{n-1}{2},\frac{1}{2})$ and $\bar{\omega}_2(r) = I_{\frac{r^2-\varrho_2^2}{r^2}}(\frac{n-1}{2},\frac{1}{2})$ for every non-vanishing $r \in \mathbb{R}$, where I is the regularized incomplete beta function, and define $\omega_1(\boldsymbol{x}) := \bar{\omega}_1(|\boldsymbol{x}|)$ and $\omega_2(\boldsymbol{x}) := \bar{\omega}_2(|\boldsymbol{x}|)$.

By formula (4.3) in Lemma 4.1 we have

$$\int_{\bar{\tau}\mathcal{B}\setminus\varrho_1\mathcal{B}^n}\omega_1(\boldsymbol{x})\,d\boldsymbol{x}=\frac{\Gamma(n/2)}{\pi^{n/2}}\int_{\mathbb{S}^{n-1}}\mathcal{C}_{\varrho_1;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}})d\boldsymbol{\xi}=\int_{\mathcal{K}\setminus\varrho_1\mathcal{B}^n}\omega_1(\boldsymbol{x})\,d\boldsymbol{x},$$

and similarly

$$\int_{\bar{r}\mathcal{B}\setminus\varrho_{2}\mathcal{B}^{n}}\omega_{2}(\boldsymbol{x})\,d\boldsymbol{x}=\frac{\Gamma(n/2)}{\pi^{n/2}}\int_{\mathbb{S}^{n-1}}\mathcal{C}_{\varrho_{2};\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}})d\boldsymbol{\xi}=\int_{\mathcal{K}\setminus\varrho_{2}\mathcal{B}^{n}}\omega_{2}(\boldsymbol{x})\,d\boldsymbol{x}.$$

With the notations in Lemma 4.3, these mean $V_1(\mathcal{K}) = V_1(\bar{r}\mathcal{B})$ and $V_2(\mathcal{K}) = V_2(\bar{r}\mathcal{B})$. Further, one can easily see that

$$1 < \frac{\omega_1(\boldsymbol{x})}{\omega_2(\boldsymbol{x})} = \frac{\bar{\omega}_1(|\boldsymbol{x}|)}{\bar{\omega}_2(|\boldsymbol{x}|)} =: q_n(|\boldsymbol{x}|), \qquad (n \text{ is the dimension})$$

is constant on every sphere, especially on $\bar{r}\mathbb{S}^{n-1}$.

As $\bar{\omega}_1$ and $\bar{\omega}_2$ are both strictly increasing, q_n is strictly decreasing if and only if

(5.1)
$$\frac{\bar{\omega}_1'(r)}{\bar{\omega}_2'(r)} < \frac{\bar{\omega}_1(r)}{\bar{\omega}_2(r)}$$

First calculate for any $n \in \mathbb{N}$ that

$$\frac{\bar{\omega}_1'(r)}{\bar{\omega}_2'(r)} = \frac{\left(1 - \frac{\varrho_1^2}{r^2}\right)^{\frac{n-3}{2}} \left(\frac{\varrho_1^2}{r^2}\right)^{-1/2} \frac{2\varrho_1^2}{r^3}}{\left(1 - \frac{\varrho_2^2}{r^2}\right)^{\frac{n-3}{2}} \left(\frac{\varrho_2^2}{r^2}\right)^{-1/2} \frac{2\varrho_2^2}{r^3}} = \frac{\left(r^2 - \varrho_1^2\right)^{\frac{n-3}{2}} \varrho_1}{\left(r^2 - \varrho_2^2\right)^{\frac{n-3}{2}} \varrho_2}$$

then consider for $n \ge 4$ that

$$\begin{aligned} \frac{\bar{\omega}_{1}(r)B\left(\frac{n-1}{2},\frac{1}{2}\right)}{\left(1-\frac{\varrho_{1}^{2}}{r^{2}}\right)^{\frac{n-3}{2}}} &= \left(1-\frac{\varrho_{1}^{2}}{r^{2}}\right)^{\frac{3-n}{2}} \int_{0}^{1-\frac{\varrho_{1}^{2}}{r^{2}}} t^{\frac{n-3}{2}} (1-t)^{\frac{-1}{2}} dt \\ &= \int_{0}^{1} s^{\frac{n-3}{2}} \left(1-s\left(1-\frac{\varrho_{1}^{2}}{r^{2}}\right)\right)^{\frac{-1}{2}} \left(1-\frac{\varrho_{1}^{2}}{r^{2}}\right) ds \\ &= -2 \int_{0}^{1} s^{\frac{n-3}{2}} \frac{d}{ds} \left(\left(1-s\left(1-\frac{\varrho_{1}^{2}}{r^{2}}\right)\right)^{\frac{1}{2}}\right) ds \\ &= -2 \left(\frac{\varrho_{1}}{r} - \frac{n-3}{2} \int_{0}^{1} s^{\frac{n-5}{2}} \left(1-s\left(1-\frac{\varrho_{1}^{2}}{r^{2}}\right)\right)^{\frac{1}{2}} ds \right) \\ &= \frac{2\varrho_{1}}{r} \left(\frac{n-3}{2} \int_{0}^{1} s^{\frac{n-5}{2}} \left(\frac{r^{2}}{\varrho_{1}^{2}} (1-s)+s\right)^{\frac{1}{2}} ds - 1\right). \end{aligned}$$

From the two equations above we deduce

$$\begin{split} \frac{\bar{\omega}_1(r)}{\bar{\omega}_2(r)} \frac{\bar{\omega}_2'(r)}{\bar{\omega}_1'(r)} &= \frac{\frac{2\varrho_1}{r} (1 - \frac{\varrho_1^2}{r^2})^{\frac{n-3}{2}} \left(\frac{n-3}{2} \int_0^1 s^{\frac{n-5}{2}} (\frac{r^2}{\varrho_1^2} (1 - s) + s)^{\frac{1}{2}} \, ds - 1\right)}{\frac{2\varrho_2}{r} (1 - \frac{\varrho_2^2}{r^2})^{\frac{n-3}{2}} \left(\frac{n-3}{2} \int_0^1 s^{\frac{n-5}{2}} (\frac{r^2}{\varrho_2^2} (1 - s) + s)^{\frac{1}{2}} \, ds - 1\right)} \frac{(r^2 - \varrho_2^2)^{\frac{n-3}{2}} \varrho_2}{(r^2 - \varrho_1^2)^{\frac{n-3}{2}} \varrho_1} \\ &= \frac{\frac{n-3}{2} \int_0^1 s^{\frac{n-5}{2}} (\frac{r^2}{\varrho_1^2} (1 - s) + s)^{\frac{1}{2}} \, ds - 1}{\frac{n-3}{2} \int_0^1 s^{\frac{n-5}{2}} (\frac{r^2}{\varrho_2^2} (1 - s) + s)^{\frac{1}{2}} \, ds - 1}{2} \ge 1, \end{split}$$

where in the last inequality we used $\varrho_1 < \varrho_2$. Thus, for $n \ge 4$ we have proved (5.1).

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Assume now, that n < 4. It is easy to see that

$$\bar{\omega}_1(r) - \bar{\omega}_2(r) = \frac{1}{B(\frac{n-1}{2}, \frac{1}{2})} \int_{1-\varrho_2^2/r^2}^{1-\varrho_1^2/r^2} t^{\frac{n-3}{2}} (1-t)^{-1/2} dt,$$

hence differentiation leads to

$$\begin{split} (\bar{\omega}_1'(r) - \bar{\omega}_2'(r)) B\Big(\frac{n-1}{2}, \frac{1}{2}\Big) \\ &= \Big(1 - \frac{\varrho_1^2}{r^2}\Big)^{\frac{n-3}{2}} \Big(\frac{\varrho_1^2}{r^2}\Big)^{-1/2} \frac{2\varrho_1^2}{r^3} - \Big(1 - \frac{\varrho_2^2}{r^2}\Big)^{\frac{n-3}{2}} \Big(\frac{\varrho_2^2}{r^2}\Big)^{-1/2} \frac{2\varrho_2^2}{r^3} \\ &= \frac{2}{r^{n-1}} \Big((r^2 - \varrho_1^2)^{\frac{n-3}{2}} \varrho_1 - (r^2 - \varrho_2^2)^{\frac{n-3}{2}} \varrho_2 \Big). \end{split}$$

This is clearly negative for all r if n = 2 and n = 3, hence

$$\frac{\bar{\omega}_1(r)}{\bar{\omega}_2(r)}\frac{\bar{\omega}_2'(r)}{\bar{\omega}_1'(r)} = \frac{\bar{\omega}_1(r)}{\bar{\omega}_2(r)} \Big(\frac{\bar{\omega}_2'(r) - \bar{\omega}_1'(r)}{\bar{\omega}_1'(r)} + 1\Big) \ge \frac{\bar{\omega}_1(r)}{\bar{\omega}_2(r)} \ge 1$$

proving (5.1) for $n \leq 3$.

Thus, $\frac{\bar{\omega}_1(r)}{\bar{\omega}_2(r)}$ is strictly monotone decreasing in any dimension, hence $\mathcal{K} \equiv \bar{r}\mathcal{B}$ follows from Lemma 4.3.

Theorem 5.2. Let $0 < \varrho_1 < \varrho_2 < \bar{r}$ and the dimension be $n \neq 3$. If \mathcal{K} is a convex body having $\varrho_2 \mathcal{B}$ in its interior, and $S_{\varrho_1;\mathcal{K}} \equiv S_{\varrho_1;\bar{r}\mathcal{B}}$, $S_{\varrho_2;\mathcal{K}} \equiv S_{\varrho_2;\bar{r}\mathcal{B}}$, then $\mathcal{K} \equiv \bar{r}\mathcal{B}$.

Proof. Let $\bar{\omega}_1(r) = (r^2 - \varrho_1^2)^{\frac{n-3}{2}} r^{2-n}$ and $\bar{\omega}_2(r) = (r^2 - \varrho_2^2)^{\frac{n-3}{2}} r^{2-n}$ for every non-vanishing $r \in \mathbb{R}$, and define $\omega_1(\mathbf{x}) := \bar{\omega}_1(|\mathbf{x}|)$ and $\omega_2(\mathbf{x}) := \bar{\omega}_2(|\mathbf{x}|)$.

By formula (4.4) in Lemma 4.2 we have

$$\int_{\bar{r}\mathcal{B}\setminus\varrho_1\mathcal{B}^n}\omega_1(\boldsymbol{x})\,d\boldsymbol{x}=\frac{1}{|\mathbb{S}^{n-2}|}\int_{\mathbb{S}^{n-1}}\mathcal{S}_{\varrho_1;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}})d\boldsymbol{\xi}=\int_{\mathcal{K}\setminus\varrho_1\mathcal{B}^n}\omega_1(\boldsymbol{x})\,d\boldsymbol{x},$$

and similarly

$$\int_{\bar{r}\mathcal{B}\setminus\varrho_{2}\mathcal{B}^{n}}\omega_{2}(\boldsymbol{x})\,d\boldsymbol{x}=\frac{1}{|\mathbb{S}^{n-2}|}\int_{\mathbb{S}^{n-1}}\mathrm{S}_{\varrho_{2};\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}})d\boldsymbol{\xi}=\int_{\mathcal{K}\setminus\varrho_{2}\mathcal{B}^{n}}\omega_{2}(\boldsymbol{x})\,d\boldsymbol{x}$$

With the notations in Lemma 4.3, these mean $V_1(\mathcal{K}) = V_1(\bar{r}\mathcal{B})$ and $V_2(\mathcal{K}) = V_2(\bar{r}\mathcal{B})$.

The ratio $\frac{\omega_1(\boldsymbol{x})}{\omega_2(\boldsymbol{x})} = \frac{\bar{\omega}_1(|\boldsymbol{x}|)}{\bar{\omega}_2(|\boldsymbol{x}|)}$ is obviously constant on every sphere, especially on $\bar{r}\mathbb{S}^{n-1}$, and it is

$$\frac{\bar{\omega}_1(r)}{\bar{\omega}_2(r)} = \begin{cases} \frac{\sqrt{r^2 - \varrho_2^2}}{\sqrt{r^2 - \varrho_1^2}} = \sqrt{1 - \frac{\varrho_1^2 - \varrho_2^2}{r^2 - \varrho_1^2}}, & \text{if } n = 2, \\ 1, & \text{if } n = 3, \\ \left(1 + \frac{\varrho_2^2 - \varrho_1^2}{r^2 - \varrho_2^2}\right)^{\frac{n-3}{2}}, & \text{if } n > 3. \end{cases}$$

Thus, $\frac{\overline{\omega}_1(r)}{\overline{\omega}_2(r)}$ is strictly monotone if the dimension $n \neq 3$, hence $\mathcal{K} \equiv \overline{r}\mathcal{B}$ follows from Lemma 4.3 for dimensions other than 3.

This theorem leaves the question open in dimension 3 if $S_{\varrho_1;\mathcal{K}} \equiv S_{\varrho_1;\bar{r}\mathcal{B}}$ and $S_{\varrho_2;\mathcal{K}} \equiv S_{\varrho_2;\bar{r}\mathcal{B}}$ imply $\mathcal{K} \equiv \bar{r}\mathcal{B}$. We have not yet tried to find an answer.

The following generalizes Theorem 3.1 for most dimensions, but only for spheres.

Theorem 5.3. Let $\varrho_1, \varrho_2 \in (0, \bar{r})$ and let \mathcal{K} be a convex body in \mathbb{R}^n having $\max(\varrho_1, \varrho_2)\mathcal{B}$ in its interior. If $S_{\varrho_1;\mathcal{K}} \equiv S_{\varrho_1;\bar{r}\mathcal{B}}$ and $C_{\varrho_2;\mathcal{K}} \equiv C_{\varrho_2;\bar{r}\mathcal{B}}$, and

(1) n = 2 or n = 3, or

(2) $n \ge 4$ and $\varrho_1 \le \varrho_2$, then $\mathcal{K} \equiv \bar{r}\mathcal{B}$.

Proof. Let $\bar{\omega}_1(r) = (r^2 - \varrho_1^2)^{\frac{n-3}{2}} r^{2-n}$ and $\bar{\omega}_2(r) = I_{\frac{r^2 - \varrho_2^2}{r^2}}(\frac{n-1}{2}, \frac{1}{2})$ for every non-vanishing $r \in \mathbb{R}$, and define $\omega_1(\boldsymbol{x}) := \bar{\omega}_1(|\boldsymbol{x}|)$ and $\omega_2(\boldsymbol{x}) := \bar{\omega}_2(|\boldsymbol{x}|)$.

By formula (4.4) in Lemma 4.2 we have

$$\int_{\bar{r}\mathcal{B}\setminus\varrho_1\mathcal{B}^n}\omega_1(\boldsymbol{x})\,d\boldsymbol{x}=\frac{1}{|\mathbb{S}^{n-2}|}\int_{\mathbb{S}^{n-1}}\mathbf{S}_{\varrho_1;\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}})d\boldsymbol{\xi}=\int_{\mathcal{K}\setminus\varrho_1\mathcal{B}^n}\omega_1(\boldsymbol{x})\,d\boldsymbol{x},$$

and by formula (4.3) in Lemma 4.1 we have

$$\int_{\bar{r}\mathcal{B}\setminus\varrho_{2}\mathcal{B}^{n}}\omega_{2}(\boldsymbol{x})\,d\boldsymbol{x}=\frac{\Gamma(n/2)}{\pi^{n/2}}\int_{\mathbb{S}^{n-1}}\mathcal{C}_{\varrho_{2};\mathcal{K}}(\boldsymbol{u}_{\boldsymbol{\xi}})d\boldsymbol{\xi}=\int_{\mathcal{K}\setminus\varrho_{2}\mathcal{B}^{n}}\omega_{2}(\boldsymbol{x})\,d\boldsymbol{x}.$$

With the notations in Lemma 4.3, these mean $V_1(\mathcal{K}) = V_1(\bar{r}\mathcal{B})$ and $V_2(\mathcal{K}) = V_2(\bar{r}\mathcal{B})$.

The ratio $\frac{\omega_2(\boldsymbol{x})}{\omega_1(\boldsymbol{x})} = \frac{\bar{\omega}_2(|\boldsymbol{x}|)}{\bar{\omega}_1(|\boldsymbol{x}|)}$ is obviously constant on every sphere, especially on $\bar{r}\mathbb{S}^{n-1}$, and it is

$$\begin{split} \frac{\bar{\omega}_2(r)}{\bar{\omega}_1(r)} &= \frac{\int_0^{1-\frac{\varrho_2^2}{r^2}} t^{\frac{n-3}{2}} (1-t)^{\frac{-1}{2}} dt}{(r^2 - \varrho_1^2)^{\frac{n-3}{2}} r^{2-n}} \\ &= \frac{\frac{2\varrho_2}{r} (1 - \frac{\varrho_2^2}{r^2})^{\frac{n-3}{2}} (\frac{n-3}{2} \int_0^1 s^{\frac{n-5}{2}} (\frac{r^2}{\varrho_2^2} (1-s) + s)^{\frac{1}{2}} ds - 1)}{\frac{1}{r} (1 - \frac{\varrho_1^2}{r^2})^{\frac{n-3}{2}}} \qquad \text{by (5.2)} \\ &= 2\varrho_1 \Big(\frac{r^2 - \varrho_2^2}{r^2 - \varrho_1^2}\Big)^{\frac{n-3}{2}} \left(\frac{n-3}{2} \int_0^1 s^{\frac{n-5}{2}} (\frac{r^2}{\varrho_2^2} (1-s) + s)^{\frac{1}{2}} ds - 1\right) \\ &= 2\varrho_1 \Big(1 + \frac{\varrho_1^2 - \varrho_2^2}{r^2 - \varrho_1^2}\Big)^{\frac{n-3}{2}} \left(\frac{n-3}{2} \int_0^1 s^{\frac{n-5}{2}} (\frac{r^2}{\varrho_2^2} (1-s) + s)^{\frac{1}{2}} ds - 1\Big) \end{split}$$

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if n > 3. For other values of n we have

$$\begin{split} \bar{\omega}_2(r) &= \frac{\int_0^{1-\frac{\varrho_2^2}{r^2}} t^{\frac{n-3}{2}} (1-t)^{\frac{-1}{2}} dt}{(r^2 - \varrho_1^2)^{\frac{n-3}{2}} r^{2-n}} \\ &= \begin{cases} (r^2 - \varrho_1^2)^{\frac{1}{2}} \int_0^{1-\frac{\varrho_2^2}{r^2}} t^{\frac{-1}{2}} (1-t)^{\frac{-1}{2}} dt, & \text{if } n = 2, \\ r \int_0^{1-\frac{\varrho_2^2}{r^2}} (1-t)^{\frac{-1}{2}} dt, & \text{if } n = 3. \end{cases} \end{split}$$

Thus, $\frac{\bar{\omega}_2(r)}{\bar{\omega}_1(r)}$ is strictly monotone increasing if n = 2, 3 and it is also strictly monotone increasing if n > 3 and $\varrho_1 \le \varrho_2$. In these cases Lemma 4.3 implies $\mathcal{K} \equiv \bar{r}\mathcal{B}$.

This theorem leaves open the case when $\rho_1 > \rho_2$ in dimensions n > 3. We have not yet tried to complete our theorem.

6 Discussion

Barker and Larman conjectured in [1, Conjecture 2] that in the plane \mathcal{M} -equisectioned convex bodies coincide, but they were unable to justify this in full⁴. Nevertheless they proved, among others, that a \mathcal{D} -isosectioned convex body \mathcal{K} in the plane is a disc concentric to the disc \mathcal{D} .

Having a convex body \mathcal{K} that is sphere-isocapped with respect to two concentric spheres raises the problem if there is a concentric ball $\bar{r}\mathcal{B}$ —obviously sphere-isocapped with respect to that two concentric spheres— that is sphere-equicapped to \mathcal{K} with respect to that two concentric spheres. The very same problem exists also for bodies that are sphere-isosectioned with respect to two concentric spheres. So we have the following range characterization problems: Let $0 < \rho_1 < \rho_2$ and let $c_1 > c_2 > 0$ be positive constants. Is there a convex body \mathcal{K} containing the ball $\rho_2 \mathcal{B}$ in its interior and satisfying

- (i) $c_1 \equiv C_{\rho_1;\mathcal{K}}$ and $c_2 \equiv C_{\rho_2;\mathcal{K}}$ (raised by Theorem 5.1)?
- (ii) $c_1 \equiv S_{\rho_1;\mathcal{K}}$ and $c_2 \equiv S_{\rho_2;\mathcal{K}}$ (raised by Theorem 5.2)?
- (iii) $c_1 \equiv S_{\rho_1;\mathcal{K}}$ and $c_1 \equiv C_{\rho_1;\mathcal{K}}$ (raised by Theorem 5.3)?

In the plane if \mathcal{M} is allowed to shrink to a point (empty interior), then $S_{\mathcal{M};\mathcal{K}}$ is the X-ray picture at a point source [3] investigated by Falconer in [2]. The method used in Falconer's article made Barker and Larman mention in [1] that in dimension 2 the convex body \mathcal{K} can be determined from $S_{\mathcal{M};\mathcal{K}}$ and $S_{\mathcal{M}';\mathcal{K}}$ if $\partial \mathcal{M}$ and $\partial \mathcal{M}'$ are intersecting each other in a suitable manner. The method in the

⁴Recently J. Kincses informed the authors in detail [5] that he is very close to finish the construction of two different \mathcal{D} -equisectioned convex bodies \mathcal{K}_1 and \mathcal{K}_2 in the plane for a disk \mathcal{D} .

anticipated proof presented in [1] decisively depends on the condition of proper intersection.

Finally we note that determining a convex body by its constant width and constant brightness [8] sounds very similar a problem as the ones investigated in this paper. Moreover also the result is analogous to Theorem 5.3.

Acknowledgements. This research was supported by the European Union and co-funded by the European Social Fund under the project "Telemedicine-focused research activities on the field of Mathematics, Informatics and Medical sciences" of project number 'TÁMOP-4.2.2.A-11/1/KONV-2012-0073".

The authors appreciate János Kincses for discussions of the problems solved in this paper.

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Á. KURUSA, Bolyai Institute, University of Szeged, Aradi vértanúk tere 1., H-6720 Szeged, Hungary; *e-mail*: kurusa@math.u-szeged.hu

T. ÓDOR, Bolyai Institute, University of Szeged, Aradi vértanúk tere 1., H-6720 Szeged, Hungary; *e-mail*: odor@math.u-szeged.hu