# On Nonpermutational Transformation Semigroups with an Application to Syntactic Complexity<sup>\*</sup>

Szabolcs Iván<sup>†</sup> and Judit Nagy-György<sup>†</sup>

#### Abstract

We give an upper bound of n((n-1)!-(n-3)!) for the possible largest size of a subsemigroup of the full transformational semigroup over n elements consisting only of nonpermutational transformations. As an application we gain the same upper bound for the syntactic complexity of (generalized) definite languages as well.

# 1 Introduction

A language is generalized definite if membership can be decided for a word by looking at its prefix and suffix of a given constant length. Generalized definite languages and automata were introduced by Ginzburg [6] in 1966 and further studied in e.g. [4, 5, 13, 15]. This language class is strictly contained within the class of star-free languages, lying on the first level of the dot-depth hierarchy [1]. This class possess a characterization in terms of its syntactic semigroup [12]: a regular language is generalized definite if and only if its syntactic semigroup is locally trivial if and only if it satisfies a certain identity  $x^{\omega}yx^{\omega} = x^{\omega}$ . This characterization is hardly efficient by itself when the language is given by its minimal automaton, since the syntactic semigroup can be much larger than the automaton (a construction for a definite language with state complexity – that is, the number of states of its minimal automaton -n and syntactic complexity - that is, the size of the transition semigroup of its minimal automaton -|e(n-1)!| is explicit in [2]). However, as stated in [14], Sec. 5.4, it is usually not necessary to compute the (ordered) syntactic semigroup but most of the time one can develop a more efficient algorithm by analyzing the minimal automaton. As an example for this line of research, recently, the authors of [9] gave a nice characterization of minimal automata of piecewise testable languages, yielding a quadratic-time decision algorithm, matching an alternative (but of course equivalent) earlier (also quadratic) characterization of [17] which improved the  $\mathcal{O}(n^5)$  bound of [16].

DOI: 10.14232/actacyb.22.3.2016.9

<sup>\*</sup>Both authors were supported by the European Union and the State of Hungary, co-financed by the European Social Fund in the framework of TÁMOP 4.2.4.A/2-11-1-2012-0001 National Excellence Program. Szabolcs Iván was also supported by NKFI grant number K108448.

<sup>&</sup>lt;sup>†</sup>University of Szeged, Hungary, E-mail: {szabivan@inf,ngyj@math}.u-szeged.hu

There is an ongoing line of research for syntactic complexity of regular languages. In general, a regular language with state complexity n can have a syntactic complexity of  $n^n$ , already in the case when there are only three input letters. There are at least two possible modifications of the problem: one option is to consider the case when the input alphabet is binary (e.g. as done in [7, 10]). The second option is to study a strict subclass of regular languages. In this case, the syntactic complexity of a class C of languages is a function  $n \mapsto f(n)$ , with f(n) being the maximal syntactic complexity a member of C can have whose state complexity is (at most) n. The syntactic complexity of several language classes, e.g. (co)finite, reverse definite, bifix–, factor– and subword-free languages etc. is precisely determined in [11]. However, the exact syntactic complexity of the (generalized) definite languages and that of the star-free languages (as well as the locally testable or the locally threshold testable languages) is not known yet.

In this note we give an upper bound for the maximal size of a subsemigroup of  $T_n$ , the transformation semigroup of  $\{1, \ldots, n\}$ , consisting of "nonpermutational" transformations only. These are exactly the (transformation) semigroups satisfying the identity  $yx^{\omega} = x^{\omega}$ . It is known that a language is definite iff its syntactic semigroup satisfies the same identity; thus as a corollary we get that the same bound is also an upper bound for the syntactic complexity of definite languages.

We also give a forbidden pattern characterization for the generalized definite languages in terms of the minimal automaton, and analyze the complexity of the decision problem whether a given automaton recognizes a generalized definite language, yielding an **NL**-completeness result (with respect to logspace reductions) as well as a deterministic decision procedure running in  $\mathcal{O}(n^2)$  time (on a RAM machine). Analyzing the structure of their minimal automata we conclude that the syntactic complexity of generalized definite languages coincide with that of definite languages.

### 2 Notation

When  $n \ge 0$  is an integer, [n] stands for the set  $\{1, \ldots, n\}$ . For the sets A and B,  $A^B$  denotes the set of all functions  $f: B \to A$ . When  $f \in A^B$  and  $C \subseteq B$ , then  $f|_C \in A^C$  denotes the restriction of f to C. When  $A_1, \ldots, A_n$  are disjoint sets, A is a set and for each  $i \in [n], f_i: A_i \to A$  is a function, then the *source tupling* of  $f_1, \ldots, f_n$  is the function  $[f_1, \ldots, f_n]: (\bigcup_{i \in [n]} A_i) \to A$  with  $a[f_1, \ldots, f_n] = af_i$  for

the unique i with  $a \in A_i$ .

 $T_n$  is the transformation semigroup of [n] (i.e.  $[n]^{[n]}$ ), where composition is understood as p(fg) := (pf)g for  $p \in [n]$  and  $f, g : [n] \to [n]$  (i.e., transformations of [n] act on [n] from the right to ease notation in the automata-related part of the paper). Elements of  $T_n$  are often written as *n*-ary vectors as usual, e.g. f =(1,3,3,2) is the member of  $T_4$  with 1f = 1, 2f = 3, 3f = 3 and 4f = 2.

When  $f : A \to A$  is a transformation of a set A, and X is a subset of A, then Xf denotes the subset  $\{xf : x \in X\}$  of A.

A transformation  $f : A \to A$  of a (finite) set A is nonpermutational if Xf = Ximplies |X| = 1 for any nonempty  $X \subseteq A$ . Otherwise it's permutational.  $NP_n$ stands for the set of all nonpermutational transformations of [n].

Another class of functions used in the paper is that of the *elevating* functions: for the integers  $0 < k \leq n$ , a function  $f : [k] \to [n]$  is elevating if  $i \leq if$  for each  $i \in [k]$  with equality allowed only in the case when i = n (note that this also implies k = n as well).

We assume the reader is familiar with the standard notions of automata and language theory, but still we give a summary for the notation.

An alphabet is a nonempty finite set  $\Sigma$ . The set of words over  $\Sigma$  is denoted  $\Sigma^*$ , while  $\Sigma^+$  stands for the set of nonempty words. The empty word is denoted  $\varepsilon$ . A language over  $\Sigma$  is an arbitrary set  $L \subseteq \Sigma^*$  of  $\Sigma$ -words.

A (finite) automaton (over  $\Sigma$ ) is a system  $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$  where Q is the finite set of states,  $q_0 \in Q$  is the start state,  $F \subseteq Q$  is the set of final (or accepting) states, and  $\delta : Q \times \Sigma \to Q$  is the transition function. The transition function  $\delta$  extends in a unique way to a right action of the monoid  $\Sigma^*$  on Q, also denoted  $\delta$  for ease of notation. When  $\delta$  is understood, we write  $q \cdot u$ , or simply qu for  $\delta(q, u)$ . Moreover, when  $C \subseteq Q$  is a subset of states and  $u \in \Sigma^*$  is a word, let Cu stand for the set  $\{pu : p \in C\}$  and when L is a language,  $CL = \{pu : p \in C, u \in L\}$ . The language recognized by  $\mathbb{A}$  is  $L(\mathbb{A}) = \{x \in \Sigma^* : q_0 x \in F\}$ . A language is regular if it can be recognized by some finite automaton.

The state  $q \in Q$  is *reachable* from a state  $p \in Q$  in  $\mathbb{A}$ , denoted  $p \preceq_{\mathbb{A}} q$ , or just  $p \preceq q$  if there is no danger of confusion, if pu = q for some  $u \in \Sigma^*$ . An automaton is *connected* if its states are all reachable from its start state.

Two states p and q of  $\mathbb{A}$  are *distinguishable* if there exists a word  $u \in \Sigma^*$  such that exactly one of pu and qu belongs to F. In this case we say that u separates p and q. A connected automaton is called *reduced* if each pair of distinct states is distinguishable.

It is known that for each regular language L there exists a reduced automaton, unique up to isomorphism, recognizing L. This automaton  $\mathbb{A}_L$  can be computed from any automaton recognizing L by an efficient algorithm called minimization and is called the *minimal automaton* of L.

The classes of the equivalence relation  $p \sim q \Leftrightarrow p \leq q$  and  $q \leq p$  are called *components* of A. A component C is *trivial* if  $C = \{p\}$  for some state p such that  $pa \neq p$  for any  $a \in \Sigma$ , and is a *sink* if  $C\Sigma \subseteq C$ . It is clear that each automaton has at least one sink and sinks are never trivial. The *component graph*  $\Gamma(\mathbb{A})$  of A is an edge-labelled directed graph  $(V, E, \ell)$  along with a mapping  $c : Q \to V$  where V is the set of the  $\sim$ -classes of A, the mapping c associates to each state q its class  $q/ \sim = \{p : p \sim q\}$  and for two classes  $p/ \sim$  and  $q/ \sim$  there exists an edge from  $p/ \sim$  to  $q/ \sim$  labelled by  $a \in \Sigma$  if and only if p'a = q' for some  $p' \sim p$ ,  $q' \sim q$ . It is known that the component graph can be constructed from A in linear time. Note that the mapping c is redundant but it gives a possibility for determining whether  $p \sim q$  holds in constant time on a RAM machine, provided Q = [n] for some n > 0 and c is stored as an array.

When  $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$  is an automaton, its transformation semigroup  $\mathcal{T}(\mathbb{A})$ 

consists of the set of transformations of Q induced by nonempty words, i.e.  $\mathcal{T}(\mathbb{A}) = \{u^{\mathbb{A}} : u \in \Sigma^+\}$  where  $u^{\mathbb{A}} : Q \to Q$  is the transformation defined as  $q \mapsto qu$ . The state complexity  $\operatorname{stc}(L)$  of a regular language L is the number of states of its minimal automaton  $\mathbb{A}_L$  while its syntactic complexity  $\operatorname{syc}(L)$  is the cardinality of its transformation semigroup  $\mathcal{T}(\mathbb{A}_L)$ . The syntactic complexity of a class of languages C is a function  $f: \mathbb{N} \to \mathbb{N}$  defined as

$$f(n) = \max\{\operatorname{syc}(L) : L \in C, \operatorname{stc}(L) \le n\},\$$

i.e. f(n) is the maximal size that the transformation semigroup of a minimal automaton of a language belonging to C can have, provided the automaton has at most n states.

# 3 Semigroups of nonpermutational transformations

Observe that  $NP_n$  is not a semigroup (i.e., not closed under composition) when n > 2. Indeed, if f = (2,3,3) and g = (1,1,2) (both being nonpermutational), then their product fg = (1,2,2) is permutational with  $\{1,2\}fg = \{1,2\}$ . (See Figure 1.)

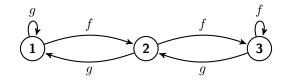


Figure 1: f and g are nonpermutational, fg is permutational

Thus, the following question is nontrivial: how large a subsemigroup of  $T_n$ , which consists only of nonpermutational transformations can be? The obvious upper bound is  $n^n$ , the size of  $T_n$ .

As a first step we give an upper bound of  $n^{n-2}$ . Observe that the following are equivalent for a function  $f : [n] \to [n]$ :

- i) f is nonpermutational;
- ii) the graph of f is a rooted tree with edges directed towards the root, and with a loop edge attached on the root;
- iii)  $f^{\omega}$ , the unique idempotent power of f is a constant function.

Here "the graph of f" is of course the directed graph  $\Gamma_f$  on vertex set [n] and with (i, j) being an edge iff if = j.

Indeed, assume f is nonpermutational. Let X be the set of all nodes of  $\Gamma_f$  lying on some closed path. (Since each node of the finite graph  $\Gamma_f$  has outdegree 1, X is nonempty.) Then Xf = X, thus |X| = 1, i.e. f has a unique fixed point Fix(f)

690

and apart from the loop edge on  $\operatorname{Fix}(f)$ ,  $\Gamma_f$  is a directed acyclic graph (DAG) with each node distinct from  $\operatorname{Fix}(f)$  having outdegree 1 – that is, a tree rooted at  $\operatorname{Fix}(f)$ , with edges directed towards the root, showing i)  $\rightarrow$  ii). Then  $f^n$  is a constant function with value  $\operatorname{Fix}(f)$ , showing ii)  $\rightarrow$  iii); finally, if Xf = X for some nonempty  $X \subseteq [n]$ , then  $Xf^{\omega} = X$ , showing |X| = 1 since the image of  $f^{\omega}$  is a singleton.

Now from ii) we get that the members of  $NP_n$  are exactly the rooted trees with edges directed towards the root on which a loop edge is attached – we call such a graph an inverted looped arborescence, or ILA for short. By Cayley's theorem on the number of labeled rooted trees over n nodes, the number of all ILAs (i.e.,  $|NP_n|$ ) is  $n^{n-2}$ , giving a slightly better upper bound.

To achieve an upper bound of n!, suppose  $S \subseteq NP_n$  is a subsemigroup of  $T_n$ . For  $i \in [n]$ , let  $S_i \subseteq S$  be the subsemigroup  $\{f \in S : \operatorname{Fix}(f) = i\}$  of S. Note that  $S_i$  is indeed a semigroup: by assumption, S is closed under composition and consists of nonpermutational transformations only, moreover, if i is the common (unique) fixed point of f and g, then it is also a fixed point of fg as well, thus  $S_i$  is closed under composition.

We give an upper bound of (n-1)! for  $|S_i|, i \in [n]$ , yielding  $|S| \leq n!$ . To this end, let  $\Gamma_i$  be the graph on vertex set [n] with (j,k) being an edge iff jf = kfor some  $f \in S_i$ . Then, apart from the trivial case when  $S_i = \emptyset$ , (i, i) is an edge in  $\Gamma_i$ , moreover *i* is a sink (since if = i for each  $f \in S_i$ ). Note that in the case when  $S_i = \emptyset$ ,  $|S_i| = 0 \le (n-1)!$  clearly holds. Observe that  $\Gamma_i$  is transitive, since if (j,k) and  $(k,\ell)$  are edges of  $\Gamma_i$ , then jf = k and  $kg = \ell$  for some  $f, g \in S_i$ ; since  $S_i$  is a semigroup, fg is also in  $S_i$  thus  $(j, \ell)$  is also an edge in  $\Gamma_i$ . Now assume some node  $j \in [n]$  is in a nontrivial strongly connected component (SCC) of  $\Gamma_i$ , i.e. j lies on some closed path. By transitivity, (j, j) is an edge of  $\Gamma_i$ , thus jf = j for some  $f \in S_i$ , thus j = i since i = Fix(f) is the unique fixed point of  $f \in S_i$ . Hence by dropping the edge (i, i) we get a DAG again, thus  $\Gamma_i$  (viewed as a relation) is a strict partial ordering of [n] with largest element i. Let  $\prec_i$  stand for this partial ordering, i.e., let  $j \prec_i k$  if and only if  $j \neq i$  and jf = k for some  $f \in S_i$ . Let us also fix some arbitrary total ordering  $<_i$  extending  $\prec_i$  and write the members of [n] in the order  $a_{i,1} <_i a_{i,2} <_i \ldots <_i a_{i,n} = i$ . Then for any  $f \in S_i$  and  $1 \le j < n$ we have  $a_{i,j} <_i a_{i,j}f$ , and  $a_{i,n}f = a_{i,n}$ . Since the number of functions  $f: [n] \to [n]$ satisfying this constraint is (n-1)!  $(a_{i,1} \text{ can get } (n-1) \text{ different possible values, } a_{i,2}$ can get (n-2) etc.), we immediately get  $|S_i| \leq (n-1)!$  as well, yielding  $|S| \leq n!$ .

Via a somewhat cumbersome case analysis we can sharpen this upper bound to n((n-1)! - (n-3)!). Without loss of generality assume that  $S_n$  is (one of) the largest of the semigroups  $S_i$  and that  $<_n$  is the usual ordering < of [n] (we can achieve this by a suitable bijection).

**Lemma 1.** Suppose for each i < j and  $k < \ell$  with  $i \neq k$  there exists a function  $f \in S_n$  with if = j and  $kf = \ell$ .

Then the following holds for each  $i, j \in [n]$  and  $f \in S_i$ :

i) if j < i, then j < jf;

ii) if  $i \leq j$ , then jf = i.

*Proof.* By assumption, the statements clearly hold for i = n. Let i < n be arbitrary and  $f \in S_i$  a transformation. Clearly if = i by the definition of  $S_i$ . Also, nf < n since  $i \neq n$  is the unique fixed point of f.

Suppose jf < j for some j. Then jf = nf has to hold: if  $jf \neq nf$ , then by assumption jfg = j and nfg = n for some  $g \in S_n$ , thus both j and n are distinct fixed points of fg, a contradiction. (See Figure 2.) This implies in particular that  $j \leq jf$  for each j < nf.

Also, if nf < i, then nfg = i and ig = n for some  $g \in S_n$ , in which case fgfg has two distinct fixed points n and i, a contradiction. (See Figure 2.) Thus  $i \leq nf$ .

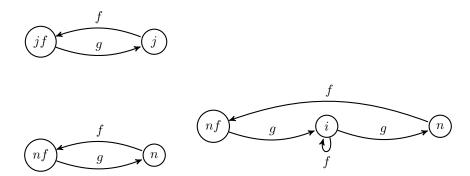


Figure 2: Left: if jf < j,  $jf \neq nf$ , then fg has two fixed points. Right: If nf < i, then fgfg has two fixed points

Assume i < nf. Then (since  $nf^n = i < nf$ ) there is some k > 0 such that  $nf^{k+1} < nf$ . If k is chosen to be the smallest possible such k, then  $nf \leq nf^k$ , yielding  $(nf^k)f < nf \leq nf^k$ , a contradiction (by  $(nf^k)f < nf^k$ , it should hold that  $(nf^k)f = nf$ , see Figure 3). Hence i = nf is the unique fixed point of f and for each j < i, j < jf indeed has to hold, showing i).

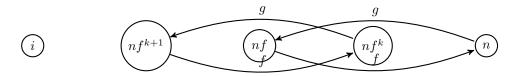


Figure 3: If i < nf, then fg has two distinct fixed points

Finally, assume i < j < jf. Then ig = j and jfg = n for some  $g \in S_n$  (if jf = n, then this latter case always gets satisfied, otherwise it's by assumption on  $S_n$ ), and fgfg has two distinct fixed points j and n. Thus we have indeed shown that nf = i is the unique fixed point of f, j < jf for each i < j and jf = i for each  $i \leq j \leq n$ .

693

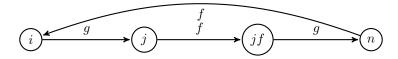


Figure 4: If i < j < jf, then fgfg has two distinct fixed points

Lemma 1 has the following corollary:

**Theorem 1.** The cardinality of any subsemigroup S of  $T_n$  consisting only of nonpermutational transformations is at most n((n-1)! - (n-3)!).

*Proof.* As before, let  $S_i$  stand for  $\{f \in S : Fix(f) = i\}$  and without loss of generality we assume that amongst them  $S_n$  is one of the largest ones, moreover  $<_n$  coincides with <.

If for each i < j and i' < j' with  $i \neq i'$  there is some  $f \in S_n$  with if = j and i'f = j', then by Lemma 1  $S_i$  can consist of at most  $(n-1)(n-2)\dots(n-i-1) = \frac{(n-1)!}{(n-i)!}$  elements (we have to choose for each j < i a larger integer and that's all since the other elements have to be mapped to i). Also  $|S_n| \leq (n-1)!$  as well. Summing up we get an upper bound for these semigroups

$$\sum_{i=1}^{n} \frac{(n-1)!}{(n-i)!} = (n-1)! \sum_{j=0}^{n-1} \frac{1}{j!} = \lfloor e(n-1)! \rfloor,$$

which comes from the facts that  $e = \sum_{j=0}^{\infty} \frac{1}{j!}$  and  $(n-1)! \sum_{j=n}^{\infty} \frac{1}{j!} < 1$ .

For the other case, suppose there exist an i < j and an i' < j' with  $i \neq i'$  such that if = j and i'f = j' do not both hold for any  $f \in S_n$ . Still, i < if for each i < n and nf = n, by definition of  $S_n$  and the assumption  $<=<_n$ . The number of such functions satisfying both if = j and i'f = j' is  $\frac{(n-1)!}{(n-i)(n-j)} \ge (n-3)!$ , hence the size of  $S_n$  is upper-bounded by (n-1)! - (n-3)!. Since  $S_n$  is the largest amongst the  $S_i$ 's and S is the disjoint union of them we get the claimed upper bound n((n-1)! - (n-3)!).

We note that the construction for the first case, yielding the upper bound  $\lfloor e(n-1)! \rfloor$  indeed constructs a semigroup B which is exactly the semigroup from [2] conjectured there to be a candidate for the maximal-size such subsemigroup.

Our proof can be viewed as a support for this conjecture and can be reformalized as follows: if there exists some i such that many transformations share this fixed point i, then the size of S is upper-bounded by  $\lfloor e(n-1)! \rfloor$  and S is isomorphic to a subsemigroup of B. The question is, whether one can construct a larger semigroup by putting not too many functions sharing a common fixed point. We also conjecture that B is a good candidate for a maximal-size subsemigroup of  $T_n$ consisting of nonpermutational transformations only.

# 4 Definite and generalized definite languages

A language L is definite if there exists a constant  $k \ge 0$  such that for any  $x \in \Sigma^*$ ,  $y \in \Sigma^k$  we have  $xy \in L \Leftrightarrow y \in L$  and is generalized definite if there exists a constant  $k \ge 0$  such that for any  $x_1, x_2 \in \Sigma^k$  and  $y \in \Sigma^*$  we have  $x_1yx_2 \in L \Leftrightarrow x_1x_2 \in L$ .

These are both subclasses of the star-free languages, i.e. can be built from the singletons with repeated use of the concatenation, finite union and complementation operations. It is known that the following decision problem is complete for **PSPACE**: given a regular language L with its minimal automaton, is L star-free? In contrast, the question for these subclasses above are tractable.

Minimal automata of these languages possess a characterization in terms of forbidden patterns. In our setting, a pattern is an edge-labelled, directed graph  $P = (V, E, \ell)$ , where V is the set of vertices,  $E \subseteq V^2$  is the set of edges, and  $\ell : E \to \mathcal{X}$  is a labelling function which assigns to each edge a variable. An automaton  $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$  admits a pattern  $P = (V, E, \ell)$  if there exists an injective mapping  $f : V \to Q$  and a map  $h : \mathcal{X} \to \Sigma^+$  such that for each  $(u, v) \in E$  labelled x we have  $f(u) \cdot h(x) = f(v)$ . Otherwise  $\mathbb{A}$  avoids P.

As an example, consider the pattern  $P_d$  on Figure 5.

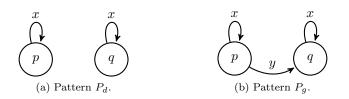


Figure 5: Patterns for definite and generalized definite languages.

#### 4.1 Syntactic complexity of definite languages

A reduced automaton avoids  $P_d$  if and only if it recognizes a definite language. Indeed, a language L is definite iff its syntactic semigroup satisfies the identity  $yx^{\omega} = x^{\omega}$ . Now assume  $L(\mathbb{A})$  admits  $P_d$  with px = p and qx = q with  $p \neq q$  and  $x \in \Sigma^+$ . If  $q_0x^{\omega} = p$ , then  $q_0x^{\omega} \neq q_0yx^{\omega}$  for a (nonempty) word y with  $q_0y = q$ . If  $q_0x^{\omega} \neq p$ , then  $q_0x^{\omega} \neq q_0yx^{\omega}$  for a (nonempty) y with  $q_0y = p$ , thus the identity is not satisfied. For the other directon, if the transition semigroup of an automaton  $\mathbb{A}$  does not satisfy  $x^{\omega} = yx^{\omega}$ , then  $p_0x_0^{\omega} \neq p_0yx_0^{\omega}$  for some  $p_0, x_0$  and y; choosing  $p = p_0x^{\omega}, q = p_0y$  and  $x_0 = x^{\omega}$  witnesses admittance of  $P_d$ . (For a more detailed discussion see e.g. [2].)

Observe that avoiding  $P_d$  is equivalent to state that each nonempty word induces a transformation with at most one fixed point, which is further equivalent to state that each nonempty word induces a non-permutational transformation: for each nonempty u, the word  $u^{|Q|!}$  fixes each state belonging to a nontrivial component of the graph of u, hence u also can have only one state in a nontrivial component, i.e. u induces a nonpermutational transformation. (Again, see [2] for a different formulation.<sup>1</sup>.)

Thus Theorem 1 has the following byproduct:

**Corollary 1.** The syntactic complexity of the definite languages is at most n((n-1)! - (n-3)!).

#### 4.2 Syntactic complexity of generalized definite languages

In this subsection we show that the syntactic complexity of definite and generalized definite languages coincide. To this end we study the structure of the minimal automata of the members of the latter class. In the process we give a (to our knowledge) new (but not too surprising) characterization of the minimal automata of generalized definite languages, leading to an **NL**-completeness result of the corresponding decision problem, as well as a low-degree polynomial deterministic algorithm.

Our first observation is the following characterization:

**Theorem 2.** The following are equivalent for a reduced automaton  $\mathbb{A}$ :

- i) A avoids  $P_q$ .
- ii) Each nontrivial component of  $\mathbb{A}$  is a sink, and for each nonempty word u and sink C of  $\mathbb{A}$ , the transformation  $u|_C : C \to C$  is non-permutational.
- iii)  $\mathbb{A}$  recognizes a generalized definite language.

*Proof.* Let  $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$  be a reduced automaton.

i) $\rightarrow$ ii). Suppose  $\mathbb{A}$  avoids  $P_g$ . Suppose that  $u|_C$  is permutational for some sink C and word  $u \in \Sigma^+$ . Then there exists a set  $D \subseteq C$  with |D| > 1 such that u induces a permutation on D. Then,  $x = u^{|D|!}$  is the identity on D. Choosing arbitrary distinct states  $p, q \in D$  and a word y with py = q (such y exists since p and q are in the same component of  $\mathbb{A}$ ), we get that  $\mathbb{A}$  admits  $P_g$  by the (p, q, x, y) defined above, a contradiction. Hence,  $u|_C$  is non-permutational for each sink C and word  $u \in \Sigma^+$ .

Now assume there exists a nontrivial component C which is not a sink. Then, pu = p for some  $p \in C$  and word  $u \in \Sigma^+$ . Since C is not a sink, there exists a sink  $C' \neq C$  reachable from p (i.e. all of its members are reachable from p). Since u induces a non-permutational transformation on C',  $x = u^{|C'|}$  induces a constant function on C'. Let q be the unique state in the image of  $x|_{C'}$ . Since C'is reachable from p, there exists some nonempty word y such that py = q. Hence, px = p, qx = q, py = q and  $\mathbb{A}$  admits  $P_g$ , a contradiction.

ii) $\rightarrow$ iii). Suppose the condition of ii) holds. We show that  $L = L(\mathbb{A})$  is generalized definite. By the assumption,  $q_0 u$  belongs to a sink for any u with  $|u| \ge |Q|$ . On

 $<sup>^{1}</sup>$ Since – up to our knowledge – [2] has not been published yet in a peer-reviewed journal or conference proceedings, we include a proof of this fact. Nevertheless, we do not claim this result to be ours, by any means.

the other hand, viewing a sink C as a (reduced) automaton  $\mathbb{C} = (C, \Sigma, \delta|_C, p, F \cap C)$ with p being an arbitrary state of C we get that the transition semigroup of  $\mathbb{C}$  consists of nonpermutational transformations only, i.e.  $L(\mathbb{C})$  is k-definite for some  $k = k_C$ . Hence choosing n to be the maximum of |Q| and the values  $k_C$  with Cbeing a sink we get that L is n-generalized definite (since the length-n prefix of udetermines the sink C to which  $q_0 u$  belongs and the length-n suffix of u, once we know C, determines the unique state in Cu).

iii) $\rightarrow$ i). Suppose  $L(\mathbb{A})$  is generalized definite. Then its syntactic semigroup satisfies  $x^{\omega}yx^{\omega} = x^{\omega}$  (see e.g. [14]).

Now assume  $\mathbb{A}_L$  admits  $P_g$  with px = p, qx = q and py = q for the nonempty words x, y and different states p, q. Then  $px^{\omega} = p$  and  $px^{\omega}yx^{\omega} = q$ , and the identity is not satisfied, thus L is not generalized definite.

In [2] it has been shown that the class of definite languages has syntactic complexity  $\geq \lfloor e \cdot (n-1)! \rfloor$ , thus the same lower bound also applies for the larger class of generalized definite languages.

**Theorem 3.** The syntactic complexity of the definite and that of the generalized definite languages coincide.

Proof. It suffices to construct for an arbitrary reduced automaton  $\mathbb{A} = (Q, \Sigma, \delta, q_0, F)$ recognizing a generalized definite language a reduced automaton  $\mathbb{B} = (Q, \Delta, \delta', q_0, F')$ for some  $\Delta$  recognizing a definite language such that  $|\mathcal{T}(\mathbb{A})| \leq |\mathcal{T}(\mathbb{B})|$ .

By Theorem 2, if  $L(\mathbb{A})$  is generalized definite and  $\mathbb{A}$  is reduced, then Q can be partitioned as a disjoint union  $Q = Q_0 \uplus Q_1 \amalg \ldots \amalg Q_c$  for some c > 0 such that each  $Q_i$  with  $i \in [c]$  is a sink of  $\mathbb{A}$  and  $Q_0$  is the (possibly empty) set of those states that belong to a trivial component. Without loss of generality we can assume that Q = [n] and  $Q_0 = [k]$  for some n and k, and that for each  $i \in [k]$  and  $a \in \Sigma$ , i < ia. The latter condition is due to the fact that reachability restricted to the set  $Q_0$  of states in trivial components is a partial ordering of  $Q_0$  which can be extended to a linear ordering. Clearly, if  $Q_0$  is nonempty, then by connectedness  $q_0 = 1$  has to hold; otherwise c = 1 and we again may assume  $q_0 = 1$ . Also,  $Q_i \Sigma \subseteq Q_i$  for each  $i \in [c]$ , and let  $|Q_1| \leq |Q_2| \leq \ldots \leq |Q_c|$ .

Then, each transformation  $f: Q \to Q$  can be uniquely written as the source tupling  $[f_0, \ldots, f_c]$  of some functions  $f_i: Q_i \to Q$  with  $f_i: Q_i \to Q_i$  for  $0 < i \leq c$ . For any  $[f_0, \ldots, f_c] \in \mathcal{T} = \mathcal{T}(\mathbb{A})$  the following hold:  $f_0(i) > i$  for each  $i \in [k]$ , and  $f_j$  is non-permutational on  $Q_j$  for each  $j \in [c]$ . For  $k = 0, \ldots, c$ , let  $\mathcal{T}_k$  stand for the set  $\{f_k: f \in \mathcal{T}\}$  (i.e. the set of functions  $f|_{Q_k}$  with  $f \in \mathcal{T}$ ). Then,  $|\mathcal{T}| \leq \prod_{0 \leq k \leq c} |\mathcal{T}_k|$ .

If  $|Q_c| = 1$ , then all the sinks of  $\mathbb{A}$  are singleton sets. Thus there are at most two sinks, since if C and D are singleton sinks whose members do not differ in their finality, then their members are not distinguishable, thus C = D since  $\mathbb{A}$  is reduced. Such automata recognize reverse definite languages, having a syntactic semigroup of size at most (n-1)! by [2], thus in that case  $\mathbb{B}$  can be chosen to an arbitrary definite automaton having n state and a syntactic semigroup of size at least |e(n-1)!| (by the construction in [2], such an automaton exists). Thus we may assume that  $|Q_c| > 1$ . (Note that in that case  $Q_c$  contains at least one final and at least one non-final state.)

697

Let us define the sets  $\mathcal{T}'_k$  of functions  $Q_i \to Q$  as  $\mathcal{T}'_0$  is the set of all elevating functions from [k] to [n],  $\mathcal{T}'_c = \mathcal{T}_c$  and for each 0 < k < c,  $\mathcal{T}'_k = Q_c^{Q_k}$ . Since  $\mathcal{T}_k \subseteq Q_k^{Q_k}$  and  $|Q_k| \leq |Q_c|$  for each  $k \in [c]$ , we have  $|\mathcal{T}_k| \leq |\mathcal{T}'_k|$  for each  $0 \leq k \leq c$ . Thus defining  $\mathcal{T}' = \{[f_0, \ldots, f_c] : f_i \in \mathcal{T}'_i\}$  it holds that  $|\mathcal{T}| \leq |\mathcal{T}'|$ .

We define  $\mathbb{B}$  as  $(Q, \mathcal{T}', \delta', q_0, F)$  with  $\delta'(q, f) = f(q)$  for each  $f \in \mathcal{T}'$ . We show that  $\mathbb{B}$  is a reduced automaton avoiding  $P_d$ , concluding the proof.

First, observe that  $\mathbb{B}$  has exactly one sink,  $Q_c$ , and all the other states belong to trivial components (since by each transition, each member of  $Q_0$  gets elevated, and each member of  $Q_i$  with 0 < i < c is taken into  $Q_c$ ). Hence if  $\mathbb{B}$  admits  $P_d$ , then pt = p and qt = q for some distinct pair  $p, q \in Q_c$  of states and  $t = [t'_0, \ldots, t'_c] \in \mathcal{T}'$ . This is further equivalent to  $pt'_c = p$  and  $qt'_c = q$  for some  $p \neq q$  in  $Q_c$  and  $t'_c \in \mathcal{T}'_c$ . By definition of  $\mathcal{T}'_c = \mathcal{T}_c$ , there exists a transformation of the form  $t = [t_0, \ldots, t_{c-1}, t'_c] \in \mathcal{T}$  induced by some word x, thus px = p and qx = q both hold in  $\mathbb{A}$ , and since p, q are in the same sink, there also exists a word y with py = q. Hence  $\mathbb{A}$  admits  $P_q$ , a contradiction.

Second,  $\mathbb{B}$  is connected. To see this, observe that each state  $p \neq 1$  is reachable from 1 by any transformation of the form  $t = [f_p, t_1, \ldots, t_c]$  where  $f_p : [k] \to [n]$  is the elevating function with  $1f_p = p$  and  $if_p = n$  for each i > 1. Of course 1 is also trivially reachable from itself, thus  $\mathbb{B}$  is connected.

Also, whenever  $p \neq q$  are different states of  $\mathbb{B}$ , then they are distinguishable by some word. To see this, we first show this for  $p, q \in Q_c$ . Indeed, since  $\mathbb{A}$  is reduced, some transformation  $t = [t_0, \ldots, t_c] \in \mathcal{T}$  separates p and q (exactly one of  $pt = pt_c$  and  $qt = qt_c$  belong to F). Since  $\mathcal{T}_c = \mathcal{T}'_c$ , we get that p and q are also distinguishable by in  $\mathbb{B}$  by any transformation of the form  $t' = [t'_0, \ldots, t'_{c-1}, t_c] \in \mathcal{T}'$ . Now suppose neither p nor q belong to  $Q_c$ . Then, since  $\{[t'_0, \ldots, t'_{c-1}] : t'_i \in \mathcal{T}'_i\} = Q_c^{Q \setminus Q_c}$ , and  $|Q_c| > 1$ , there exists some  $t = [t'_0, \ldots, t'_{c-1}]$  with  $pt \neq qt$ , thus any transformation of the form  $[t'_0, \ldots, t'_{c-1}, t_c] \in \mathcal{T}'$  maps p and q to distinct elements of  $Q_c$ , which are already known to be distinguishable, thus so are p and q. Finally, if  $p \in Q_c$  and  $q \notin Q_c$ , then let  $t_c \in \mathcal{T}_c$  be arbitrary and  $t' = [t'_0, \ldots, t_{c-1}] \in Q_c^{Q \setminus Q_c}$ with  $qt' \neq pt_c$ . Then  $[t', t_c]$  again maps p and q to distinct states of  $Q_c$ .

Thus  $\mathbb{B}$  is reduced, concluding the proof:  $\mathbb{B}$  is a reduced automaton recognizing a definite language and having a syntactic semigroup  $\mathcal{T}'$  with  $|\mathcal{T}'| \geq |\mathcal{T}|$ .  $\Box$ 

#### 4.3 Complexity issues

Using the characterization given in Theorem 2, we study the complexity of the following decision problem GENDEF: given a finite automaton  $\mathbb{A}$ , is  $L(\mathbb{A})$  a generalized definite language?

#### Theorem 4. Problem GENDEF is NL-complete.

*Proof.* First we show that GENDEF belongs to **NL**. By [3], minimizing a DFA can be done in nondeterministic logspace. Thus we can assume that the input is already

minimized, since the class of (nondeterministic) logspace computable functions is closed under composition.

Consider the following algorithm:

- 1. Guess two different states p and q.
- 2. Let s := p.
- 3. Guess a letter  $a \in \Sigma$ . Let s := sa.
- 4. If s = q, proceed to Step 5. Otherwise go back to Step 3.
- 5. Let p' := p and q' := q.
- 6. Guess a letter  $a \in \Sigma$ . Let p' := p'a and q' = q'a.
- 7. If p = p' and q = q', accept the input. Otherwise go back to Step 6.

The above algorithm checks whether A admits  $P_g$ : first it guesses  $p \neq q$ , then in Steps 2–4 it checks whether q is accessible from p, and if so, then in Steps 5–7 it checks whether there exists a word  $x \in \Sigma^+$  with px = p and qx = q. Thus it decides<sup>2</sup> the complement of GENDEF, in nondeterministic logspace; since  $\mathbf{NL} = \operatorname{co}\mathbf{NL}$ , we get that GENDEF  $\in \mathbf{NL}$  as well.

For **NL**-completeness we recall from [8] that the reachability problem for DAGs (DAG-REACH) is complete for **NL**: given a directed acyclic graph G = (V, E) on V = [n] with  $(i, j) \in E$  only if i < j, is n accessible from 1? We give a logspace reduction from DAG-REACH to GENDEF as follows. Let G = ([n], E) be an instance of DAG-REACH. For a vertex  $i \in [n]$ , let  $N(i) = \{j : (i, j) \in E\}$  stand for the set of its neighbours and let d(i) = |N(i)| < n denote the outdegree of i. When  $j \in [d(i)]$ , then the jth neighbour of i, denoted n(i, j) is simply the jth element of N(i) (with respect to the usual ordering of integers of course). Note that for any  $i \in [n]$  and  $j \in [d(i)]$  both d(i) and the n(i, j) (if exists) can be computed in logspace.

We define the automaton  $\mathbb{A} = ([n+1], [n], \delta, 1, \{n+1\})$  where

$$\delta(i,j) = \begin{cases} n+1 & \text{if } (i=n+1) \text{ or } (j=n) \text{ or } (i < n \text{ and } d(i) < j); \\ 1 & \text{if } i=n \text{ and } j < n; \\ n(i,j) & \text{otherwise.} \end{cases}$$

Note that A is indeed an automaton, i.e.  $\delta(i, j)$  is well-defined for each i, j.

We claim that A admits  $P_g$  if and only if n is reachable from 1 in G. Observe that the underlying graph of A is G, with a new edge (n, 1) and with a new vertex n + 1, which is a neighbour of each vertex. Hence,  $\{n + 1\}$  is a sink of A which is reachable from all other states. Thus A admits  $P_g$  if and only if there exists

698

<sup>&</sup>lt;sup>2</sup>Note that in this form, the algorithm can enter an infinite loop which fits into the definition of nondeterministic log*space*. Introducing a counter and allowing at most n steps in the first cycle and at most  $n^2$  in the second we get a nondeterministic algorithm using logspace and polytime, as usual.

a nontrivial component of  $\mathbb{A}$  which is different from  $\{n + 1\}$ . Since in G there are no cycles, such component exists if and only if the addition of the edge (n, 1) introduces a cycle, which happens exactly in the case when n is reachable from 1. Note that it is exactly the case when 1x = 1 for some word  $x \in \Sigma^+$ .

What remains is to show that the *reduced* form  $\mathbb{B}$  of  $\mathbb{A}$  admits  $P_g$  if and only if  $\mathbb{A}$  does. First, both 1 and n + 1 are in the connected part  $\mathbb{A}'$  of  $\mathbb{A}$ , and are distinguishable by the empty word (since n + 1 is final and 1 is not). Thus, if  $\mathbb{A}$ admits  $P_g$  with 1x = 1 and (n + 1)x = n + 1 for some  $x \in \Sigma^+$ , then  $\mathbb{B}$  admits  $P_g$ with h(1)x = h(1) and h(n+1)x = h(n+1) (with h being the homomorphism from the connected part of  $\mathbb{A}$  onto its reduced form). For the other direction, assume  $h(p)x_0 = h(p)$  for some state  $p \neq n+1$  (note that since n+1 is the only final state,  $p \neq n+1$  if and only if  $h(p) \neq h(n+1)$ ). Let us define the sequence  $p_0, p_1, \ldots$ of states of  $\mathbb{A}$  as  $p_0 = p$ ,  $p_{t+1} = p_t x_0$ . Then, for each  $i \geq 0$ ,  $h(p_i) = h(p)$ , thus  $p_i \in [n]$ . Thus, there exist indices  $0 \leq i < j$  with  $p_i = p_j$ , yielding  $p_i x_0^{j-i} = p_i$ , thus  $\mathbb{A}$  admits  $P_g$  with  $p = p_i$ , q = n + 1,  $x = x_0^{j-i}$  and y = n.

Hence, the above construction is indeed a logspace reduction from DAG-REACH to the complement of GENDEF, showing NL-hardness of the latter; applying  $\mathbf{NL} = \operatorname{co}\mathbf{NL}$  again, we get NL-hardness of GENDEF itself.

It is worth observing that the same construction also shows **NL**-hardness (thus completeness) of the problem whether the input automaton accepts a definite language.

Thus, the complexity of the problem is characterized from the theoretic point of view. However, nondeterministic algorithms are not that useful in practice. Since  $\mathbf{NL} \subseteq \mathbf{P}$ , the problem is solvable in polynomial time – now we give an efficient (quadratic) deterministic decision algorithm:

- 1. Compute  $\mathbb{A}' = (Q, \Sigma, \delta, q_0, F)$ , the reduced form of the input automaton  $\mathbb{A}$ .
- 2. Compute  $\Gamma(\mathbb{A}')$ , the component graph of  $\mathbb{A}'$ .
- 3. If there exists a nontrivial, non-sink component, reject the input.
- 4. Compute  $\mathbb{B} = \mathbb{A}' \times \mathbb{A}'$  and  $\Gamma(\mathbb{B})$ .
- 5. Check whether there exists a state (p,q) of  $\mathbb{B}$  in a nontrivial component (of  $\mathbb{B}$ ) for some  $p \neq q$  with p being in the same sink as q in A. If so, reject the input; otherwise accept it.

The correctness of the algorithm is straightforward by Theorem 2: after minimization (which takes  $\mathcal{O}(n \log n)$  time) one computes the component graph of the reduced automaton (taking linear time) and checks whether there exists a nontrivial component which is not a sink (taking linear time again, since we already have the component graph). If so, then the answer is NO. Otherwise one has to check whether there is a (sink) component C and a word  $x \in \Sigma^+$  such that  $f_x|_C$  has at least two different fixed points. Now it is equivalent to ask whether there is a state (p,q) in  $\mathbb{A}' \times \mathbb{A}'$  with p and q being in the same component and a word  $x \in \Sigma^+$  with (p,q)x = (p,q). This is further equivalent to ask whether there is a (p,q) with p,q being in the same sink such that (p,q) is in a nontrivial component of  $\mathbb{B}$ . Computing  $\mathbb{B}$  and its components takes  $\mathcal{O}(n^2)$  time, and (since we still have the component graph of  $\mathbb{A}$ ) checking this condition takes constant time for each state (p,q) of  $\mathbb{B}$ , the algorithm consumes a total of  $\mathcal{O}(n^2)$  time.

Hence we have a low-degree polynomial-time upper bound:

**Theorem 5.** Problem GENDEF can be solved in  $\mathcal{O}(n^2)$  deterministic time in the RAM model of computation.

# 5 Conclusion, further directions

The forbidden pattern characterization of generalized definite languages we gave is not surprising, based on the identities of the pseudovariety of (syntactic) semigroups corresponding to this variety of languages. Still, using this characterization one can derive efficient algorithms for checking whether a given automaton recognizes such a language. Though we could not compute an exact function for the syntactic complexity, we still managed to show that these languages are not "more complex" than definite languages under this metric. Also, we gave a new upper bound for that.

The exact syntactic complexity of definite languages is still open, as well as for other language classes higher in the dot-depth hierarchy – e.g. the locally (threshold) testable and the star-free languages.

# References

- R. S. Cohen, J. Brzozowski. Dot-Depth of Star-Free Events. Journal of Computer and System Sciences 5(1), 1971, 1–16.
- [2] J. Brzozowski, D. Liu. Syntactic Complexity of Finite/Cofinite, Definite, and Reverse Definite Languages. http://arxiv.org/abs/1203.2873
- [3] S. Cho, D. T. Huynh. The parallel complexity of finite-state automata problems. Inform. Comput. 97, 122, 1992.
- [4] M. Čirič, B. Imreh, M. Steinby. Subdirectly irreducible definite, reverse definite and generalized definite automata. Publ. Electrotechn. Fak. Ser. Mat., 10, 1999, 69–79.
- [5] F. Gécseg, B. Imreh. On isomorphic representations of generalized definite automata. Acta Cybernetica 15, 2001, 33–44.
- [6] A. Ginzburg. About some properties of definite, reverse-definite and related automata. IEEE Trans. Electronic Computers EC-15, 1966, 809–810.
- [7] M. Holzer, B. König. On deterministic finite automata and syntactic monoid size. Theoretical Computer Science 327(3), 319–347, 2004.

700

- [8] Neil D. Jones, Y. Edmund Lien and William T. Laaser: New problems complete for nondeterministic log space. THEORY OF COMPUTING SYSTEMS Volume 10, Number 1 (1976), 1-17.
- [9] O. Klíma, L. Polák. Alternative Automata Characterization of Piecewise Testable Languages. Accepted to DLT 2013.
- [10] B. Krawetz, J. Lawrence, J. Shallit. State Complexity and the Monoid of Transformations of a Finite Set. Proc. of Implementation and Application of Automata, LNCS 3317, 2005, 213–224.
- [11] B. Li. Syntactic Complexities of Nine Subclasses of Regular Languages. Master's Thesis.
- [12] D. Perrin. Sur certains semigroupes syntactiques. Séminaires de l'IRIA, Logiques et Automates, Paris, 1971, 169–177.
- [13] T. Petkovič, M. Čirič, S. Bogdanovič. Decomposition of automata and transition semigroups. Acta Cybernetica 13, 1998, 385–403.
- [14] J-É. Pin. Syntactic semigroups. Chapter 10 in Handbook of Formal Languages, Vol. I, G. Rozenberg et A. Salomaa (eds.), Springer Verlag, 1997, 679–746.
- [15] M. Steinby. On definite automata and related systems. Ann. Acad. Sci. Fenn., Ser. A I 444, 1969.
- [16] J. Stern. Complexity of some problems from the theory of automata. Information and Control 66, 1985, 163–176.
- [17] A. N. Trahtman. Piecewise and local threshold testability of DFA. Proc. of FCT 2001, LNCS 2038 (2001), 347–358.

Received 19th July 2014